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28 December 1945

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From:

Chief, Naval Technical Mission to Japan.

To:

Chief of Naval Operations.

Subject:

Target Report - Japanese Submarine and Shipborne Radar.

Reference: (a)"Intelligence Targets Japan" (DNI) of 4 Sept. 1945.

- Subject report, covering Target E-Ol of Fascicle E-l of reference (a), is submitted herewith.
- 2. The investigation of the target and the target report were accomplished by Lieut. A. A. Lang, USNR, assisted by Lieut. W. G. Lamb, USNR, and Lt. (jg) S. H. Kadish, USNR, and S. E. Pulis, ETM2c, USNR, who also acted as interpreters.

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JAPANESE SUBMARINE AND SHIPBORNE RADAR

"INTELLIGENCE TARGETS JAPAN" (DNI) OF 4 SEPT. 1945
FASCICLE E-1, TARGET E-01

DECEMBER 1945

U.S. NAVAL TECHNICAL MISSION TO JAPAN

SUMMARY

ELECTRONICS TARGETS

JAPANESE SUBMARINE AND SHIPBORNE RADAR

The radars in use on Japanese ships were all of conventional design and mediocre construction. None of the production models or experimental equipments were found to have any unusual design features or any exceptionally high performance parts or components except a unique duplexing system used with the Mark 2 Model 2 radar. Only three radar models were in use on surface ships and submarines at the end of the war, Type 3 Mark 1 Model 3 and Type 2 Mark 2 Model 1 for air search and the Mark 2 Model 2 for surface search. There was no fire control radar as such in use. A modified version of the Mark 2 Model 2 radar was used for fire control as well as surface search but results were in general unsatisfactory. The radars listed above and the history of radar development, installation methods, procedures and difficulties, maintenance techniques and operational procedures are described.

Several new equipments in the test stage and intended as replacements for the Mark 2 Model 2 radar are discussed.

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REFERENCES

Activities and Targets Investigated:

Headquarters of Second Naval Technical Institute, Kanazawa, YOKOHAMA. Meguro Laboratory of Second Naval Technical Institute, Meguro, TOKYO. Tsukishima Naval Radar Experimental Station, TOKYO. Yokosuka Naval Base. Kure Navy Yard. Various Japanese Combatant Vessels.

Japanese Personnel Interrogated:

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- Capt. H. TAKAHARA Head of the Fourtn Section of the Second Naval Technical Institute (Radar intercept equipment, radio beacons and direction finders).
- Captain and Dr. Y. ITO Head of the First and Second Sections of Second Naval Technical Institute (Fundamental Research). Specialist on cent_meter techniques.
- Comdr. OHNO Electronics Officer, Kure Navy Yard. Installation and
- operation of rudar equipment. Lt. Comdr. (Tech.) T. HYODO Researcher of materials and components for high frequency use.
- Lt. Comdr. (Tech.) S. MORI Specialist on centimeter techniques. Worked on design of the Mark 2 Model 2 radar.
- Lt. Comdr. (Tech.) O. OKAMURA Researcher of tubes for centimeter wave applications.
- Lt. Comdr. S. MATSUI Head of research at Yokosuka Naval Base on the installation of shipborne and land based radio and radar.
- Lt. Comdr. UCHIDA Radar instructor at ordnance school, Yokosuka Naval Base.
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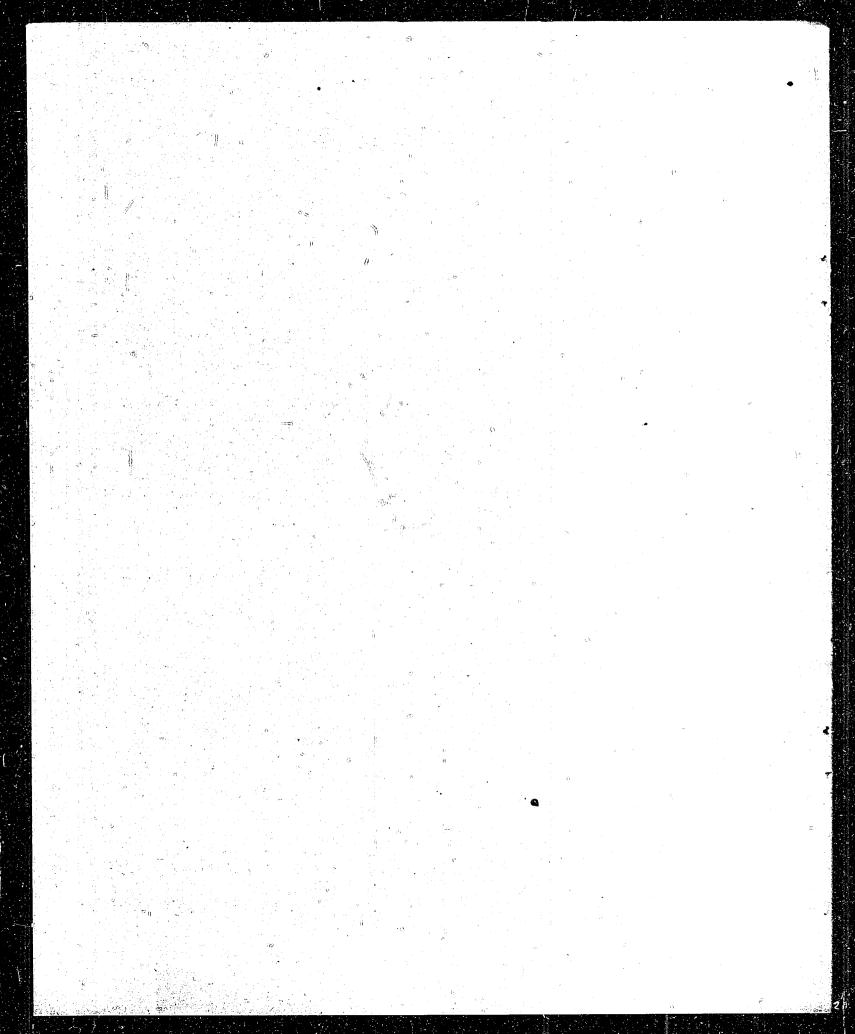
 Mr. H. SHINKAWA Researcher on meter wave radars (L2, L3, S3, S24,
- N6, M13). Mr. M. HATIYAMA Researcher on high frequency circuits for centimeter radar.

INTRODUCTION

This report attempts to outline the state of development of the radar equipment installed aboard Japanese naval vessels at the end of the war and the extent to which operational and maintenance procedures had been developed.

The operational and installation data included were obtained through the interrogation of navy yard engineers at the Kure and Yokosuka Navy Yards and from interrogations conducted aboard submarines, destroyers, and aircraft carriers in Kure Harbor. The technical data was largely obtained from the Second Naval Research Establishment at TOKYO and through interrogation of engineers concerned with the design and production of the equipment.

Documents concerning the equipment mentioned in the report will be available at the Washington Document Center.



THE REPORT

Part I
DEVELOPMENT AND PRODUCTION OF SHIPBOARD RADAR EQUIPMENT

A. History

Interrogations indicated that the first information available in Jar on any type of electronic detecting equipment was based upon a report of the ultra short wave iceberg detecting equipment installed on the French liner NORMANDIE and inspected in New York Harbor by a Japanese engineer. The next information was received early in 1941 in the form of a report from Germany which described the principles of radar, but gave no details of construction. This report resulted in the beginning of Japanese radar research in April of the same year. The design of the first equipment was completed early in 1942.

B. Research and Production Allocation Methods Used

The organization of research and development and the production allocation methods used are mentioned because many of the troubles consistently experienced with electronic equipment in the Japanese Fleet are believed to be a direct result of such organization and methods. Until January 1945, research and production were carried out on a component basis rather than on a complete equipment basis. The research group and the company assigned to produce a unit were given little insight into the design and manufacture of the other components of the equipment and little information on how the equipment would later be used in the field. This fact, coupled with an apparent total lack of provision for informing research and production personnel of service deficiencies, resulted in a very poor modification program. The organization of the Second Naval Technical Institute in January 1945 to consolidate all research activities under one head was an apparent attempt to rectify this condition.

Part II INSTALLATION OF EQUIPMENT

A. Type Allowance

Tabulation of Shipborne Radar Installations

	Type 2 Mark 2 Model 1 Radar	Type 3 Mark 1 Model 3 Radar	Mark 2 Model 2 Radar	Radar cm-wave	Intercept m-wave
Battleships FUSO class ISE class NAGATO class KONGO class YAMATO class	1 1 1	2 2 3 2 2	N N N N N	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1
Cruisers MYOKO class TAKAO class FURUTAKA class AOBA class KUMA class	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	2 2	2 2 1	1 1 1	1 1 1 1

	Type 2	Type 3	Mark 2	Radar	Intercept
	Mark 2 Model 1 Radar	Mark 1 Model 3 Radar	Model 2 Radar	cm-wave	m-wave
NAGARA class MOGAMI class TONE class AGANO class OYODO class	1 1 1	2222	2 2 2 2	1 1 1 1	1 1 1 1
Aircraft Carriers AKAGI class UNRYU class SHOKAKU class ZUIHO class JUNYO class TAIYO class TAIHO class SHINANO class	3 N N N N	3 22222	1	1 1 1 1 1	1 1 1 1 1 1 1
Destroyers MINEKAZE class KAMIKAZE class AKIZUKI class KURI class WAKATAKE class All other classes		1 2 1 1	1 1 1	1	1 1 1 1
Coast Defense Boats Minesweeper	3	1	1	1	1
1, 7, 13 classes 19 class		1	1	1	1 1
Submarine Chasers 1 class 14 class		<u>1</u>	1		1
Submarines I-400 class I-10 class Ro-100 class		2 1 1	1] 1 1	, 1 , 1
Transports First class Second class		1	1		1 1
Torpedo Boats		1			1
Minelayers		1 or	1		1
Patrol Ships		1 00			1

Remarks

- 1. There are some coast defense boats without cm-wave radar intercept receivers.
- 2. Some first class transports have Type 3 Mark 1 Model 3 radar.

B. Arrangement of Equipment

A Shipboard Installation Instruction Book, forwarded to WDC, (NavTechJap Document No. ND21-6276) contains installation notes and inter-connection wiring diagrams for the shipboard radar equipment and intercept receivers in use at the end of the war. No installation of electronic jamming equipment in naval vessels existed at the time of surrender. A large portion of the shipboard radar installation work done during the latter part of the war was accomplished at Kure Navy Yard under the direction of Commander OHNO, the former radar material officer. Through him, the installations described below were investigated because they were typical and represented the best and most complete installation jobs.

It was general practice to select compartments that provided the shortest antenna runs and yet were large enough to accomodate a complete equipment. Each equipment usually occupied its own compartment. Separation of duplicate equipments was accomplished to provide the best possible damage control. An example of this practice was noted in CV KATSURAGE, in which two air search radars were installed in the island structure but separated as much as possible and a third air search radar was installed on a retracting platform located about amidships on the port side of the flight deck. The actual arrangement of equipment in compartments was left largely to the discretion of the navy yard making the installation. As a result, little standardization existed. Apparently little thought was given in the arrangement plan either to the ease of servicing or the methods of operation to be used. Figure 1 illustrates the crowded conditions existing in a typical Mark 2 Model 2 Modification 4 fire control and surface search installation. Admittedly such an arrangement made difficult the problem of reaching simultaneous ranges and bearings by two operators. A technician adjusting the various controls made the task almost impossible. The location of the transmitter and rectifier in the crowded operating spaces usually resulted in a larger heat dissipation than the inadequate ventilation system could handle. This problem was largely solved by avoiding continuous operation.

No plotting facilities were observed in the radar compartment of any Japanese vessel. The photographs and index sketch contained in Eclosure (A) show the arrangement and installation in the forward air search radar compartment and the fire control and surface search radar compartment of a TERUTSUKI class destroyer. Enclosures (B), (C) and (D) include photographs and index sketches of the Mark 2 Model 2 Modification 4, the Type 2 Mark 2 Model 1 Modification 2, and one of two Type 3 Model 1 Model 3 radars installed in CV KATSURAGI. The sketches show the general arrangement of these compartments and orient the photographs.

Intercept receivers were installed in the same compartment as the radars and were usually given some preference in location since they were normally manned continuously while underway.

C. Power Supplier and Cabling

The 10 centimeter surface search and fire control equipments operated on a special motor-alternator. The output from this unit, in the case of fire control installations, was fed into a voltage stabilizer that produced a very constant power source. CV KATSURAGI, which was one of the most modern combatant vessels still afloat at the end of the war, produced only direct current from her main generators, and all radar equipments operated from individual motor-alternators. The motor-alternators were usually tied into the main

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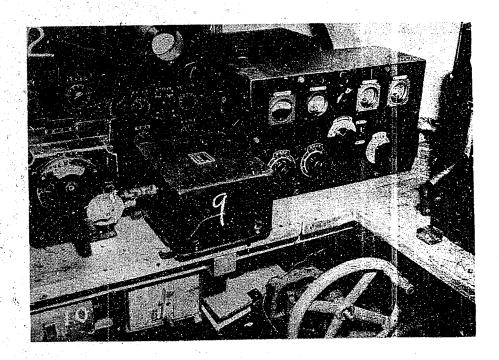


Figure 1 MARK 2 MODEL 2 MODIFICATION 4 RADAR INSTALLED IN DD HANAZUKI

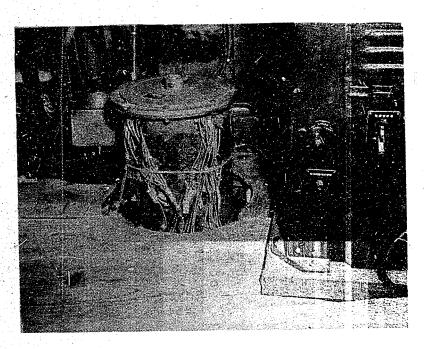


Figure 2

CABLE TRUNK IN AIR SEARCH RADAR
INSTALLATION IN CV KATSURAGI

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power distribution panel which could transfer them to an emergency generator when such units were installed.

Interconnection wiring was universally poor and such connections as shown in Figure 2 were not uncommon. Most of the cables used were armoured but in many cases the cables were permitted to pass through decks and bulkheads without any protection against chafing. Bonding of cable shields was poorly done and in many cases was accomplished to remove trouble from the equipment rather than as a part of the original installation. In a number of cases wood was used on compartment bulkheads to facilitate cable clamping.

D. Shock Mounting

Shock mounting was used in only the most critical compartments such as the transmitter and indicators, while the rest of the units were either bolted to wooden tables or to brackets welded to the deck. The mounts used were in general constructed similar to standard lord mounts. Figure 3 shows a Mark 2 Model 2 Modification 4 transmitter (1) on shock mounts with the receiver (3) and the voltage controller (4) bolted directly to a wooden platform and the deck respectively. Although considerable trouble was experienced with tubes, the cause was said to be a result of non-uniformity in production rather than the shock of gunfire.

E. R. F. Transmission Liner and Antennas

The installation of the 75 millimeter round wave guide for the 10 centimeter wave equipment was carried out in a conventional manner using standard flange connections. It was claimed that little trouble was experienced with moisture in the line and that the zinc plating stood up well, although an inspection of one run that was removed from a destroyer showed the plating to be in bad condition.

Simple two wire lines were used for the installation of all air search radar on surface vessels. Coaxial lines were used for submarine installations. Figure 4 shows a typical duplexer installation for a Type 3 Mark 1 Model 3 equipment. Various types of flexible and rigid coaxial lines were in use for interconnection wiring and submarine installations. Further information on the specifications and construction of these lines may be obtained from Nav-TechJap Report, "Japanese R. F. Transmission Lines, Wave Guides, Wave Guide Fittings, and Dielectric Materials," Index No. E-20.

Figures 5 and 6 show a typical installation of Mark 2 Model 2 Modification 4 and Type 3 Mark 1 Model 3 antennas on a TERUTSUKI class destroyer. The photographs were taken from the forward edge of the director and from just abaft the stack, respectively. The horn type antenna shown (see Figure 5) is an enlarged version used with fire control installations. The small box to the right of the antenna pedestal houses the antenna control selsyns. The Type 3 Mark 1 Model 3 antenna shown just forward of the foremast in Figure 6 is a typical air search antenna installation. This type of antenna was usually constructed by the navy yard making the installation and slight variations in mechanical construction were noted. A second air search antenna of this type was installed on the mainmast of this class of destroyers while the equipment itself was installed in the radio transmitter room directly below the mast. Figure 7 shows this antenna installation.

Modification 3 (meter wave) intercept receiver antennas were usually installed with the non-directional metox antenna secured to the yardarm and the directional racket type antenna mounted on a small platform just above the air search antenna. Figure 8 shows a typical installation in an aircraft carrier. In this case two sets of metox and racket antennas may be seen, one set for each air search radar installed in the island structure. The Model 3 (centimeter wave) intercept receiver utilized the hand-held parabolic antenna and fixed installations seem to have been made only on submarines.

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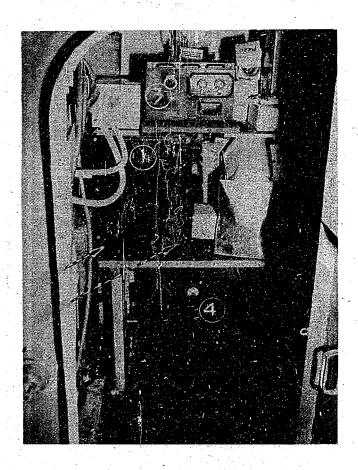




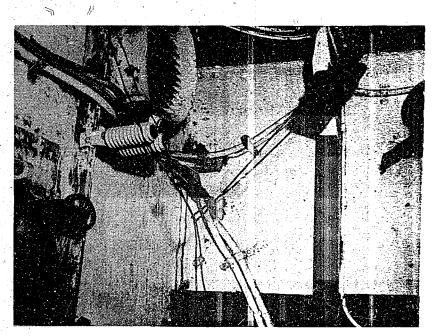
Figure 3 MARK 2 MODEL 2 RADAR INSTALLATION IN DD HANAZUKI

Figure 4

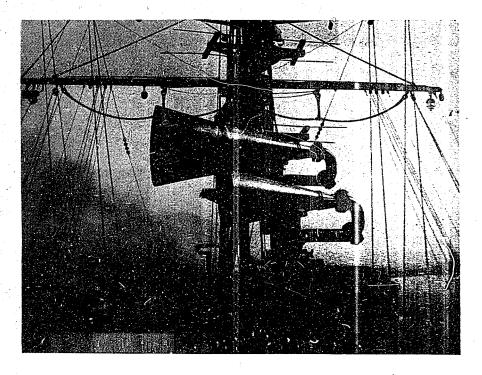
DUPLEXER FOR TYPE 3 MARK 1 MODEL 3

INSTALLATION IN DD HANAZUKI





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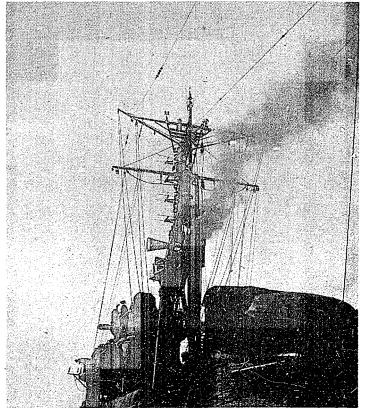




Figure 5
ANTENNA INSTALLATION IN DD HANZUKI



Figure 6
ANTENNA INSTALLATION IN DD HANAZUKI

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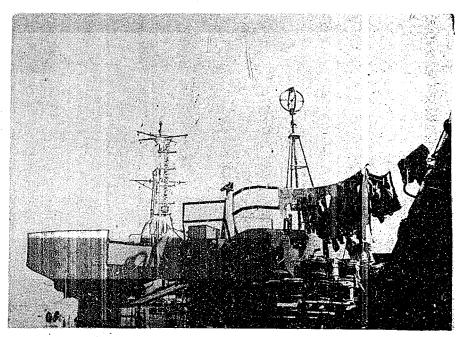


Figure 7
ANTENNA INSTALLATION IN DD HANAZUKI

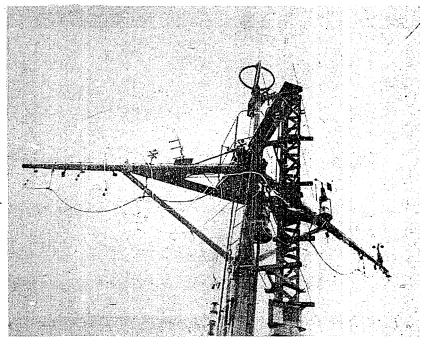


Figure 8

AIR SEARCH AND INTERCEPT RECEIVER ANTENNA
INSTALLATION IN CV KATSURAGI

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Figure 9 shows what was claimed to be the latest antenna arrangement for submarines. The single horn Mark 2 Model 2 Modification 3 antenna is not shown but was mounted just forward of the conning tower.

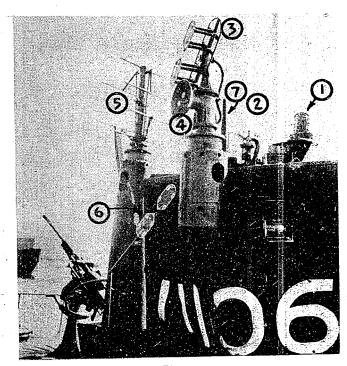


Figure 9
ANTENNÁ INSTALLATION IN SS I-106

The water seal for the wave guide of this equipment consisted of a rubber seal inserted just below the rotary joint and one safty gate valve located in the radar compartment about two meters from the pressure hull. The single non-directional dipole (1) was used both for radio transmitting and as the transmitting antenna for the Type 3 Mark 1 Model 3 radar. Details on coaxial connections and switching are shown in the Shipboard Installation Instructions Book, (NavTechJap Document No. ND21-6276). The YAGI antenna (5) was used as the air search receiving antenna. The combination racket antenna (3) and the parabolic antenna (4) were alleged to be the latest in intercept receiver antenna installations and the first and only one of this type completed at the end of the war. Fixed racket antenna (6) were mounted on both sides of the conning tower and in some cases, to reduce water resistance, were installed on the inside of the conning tower behind rubber or fabric inserts. The small cylindrical antenna (1) is the new type used with the ultra long wave receiver for underwater reception. The non-directional metox antenna is identified as (2) in Figure 9.

All directional radar antennas and the racket type intercept receiver antennas had a mechanical control system. In addition to the mechanical system, the 10 centimeter fire control installations had an electric motor drive with selsyn control. Some of the air search installations also had a simple motor drive.

Part III MAINTENANCE IN THE FLEET

A. Maintenance Personnel

All combatant vessels of destroyer size and above had at least one electronic technical officer who was usually an electrical engineering graduate and who may or may not have had special radar training before reporting aboard. An officer of similar qualifications was also assigned to the larger submarines. In the maintenance of equipment this officer was assisted by a number of enlisted technicians who, after taking a general electronic course in school, specialized in either radar, radio, or sonar after reporting aboard. The number of technicians found aboard DD HANAZUKI, believed to be representative, consisted of three radar specialists, two radio specialists, and two sonar specialists.

B. <u>Maintenance Procedures</u>

All maintenance records had been burned by the Japanese on the day rollowing the surrender and little data was available. It was stated that a maintenance log was normally kept, but little in the way of a routine preventative maintenance program was in effect. The Mark 2 Model 2 equipment was expected to operate only a small percentage of the time. However, considerable difficulty was experienced in maintaining it so that it operated satisfactorily 80% of the time that it was needed. The Type 3 Mark 1 Model 3 equipment was stated to operate satisfactorily an average of 95% of the time that this equipment was needed. Although the Type 2 Mark 2 Model 1 Modification 2 air search equipment gave little trouble, its operation was never considered satisfactory due to the use of acorn type tubes as pre-amplifiers which resulted in a low receiver sensitivity at 200 megacycles. The Model 3 and the Modification 3 intercept receivers were said to give little trouble except for routine tube failures.

The majority of failures were due to vacuum tubes and resistors. Although the same resistors continually failed, little if anything seems to have been done about changing design or ratings in installed equipment or in later production of the same models. There was a great variation in the life expectancy of vacuum tubes and they were a major source of trouble.

OPERATIONAL PROCEDURES EMPLOYED AND PERFORMANCE DATA

A. Operational Procedures Employed Aboard A TERUTSUKI Class Destroyer

The Mark 2 Model 2 Modification 4 fire control and surface search radar was manned by two operators, one using the main indicator to read ranges and the other the small oscilloscope to read bearings by the maximum amplitude method. Four additional men and one technical radar officer were also in the compartment to operate the intercept receiver and the telephones. Figure 1 and Enclosure (A) show the arrangement of equipment in this installation.

The equipment was operated only during periods of impending battle or during periods of extremely poor visibility. It was seldom used for station keeping, since its minimum range was approximately 1500 meters. The primary function of the equipment on the destroyer was to furnish ranges every 15 seconds to gunnery plot. Radar bearings were used only when visual bearings could not be obtained. Selsyn transmission of both range and bearing information was available to gunnery plot and to the individual gun mounts. Both ranges and bearings were also furnished the chief radar officer on the bridge. This officer usually attempted to maintain a rough plot from the data received and to provide the captain with evaluated radar information. Facilities were available so that a target could be designated electrically from the bridge to a match-the-pointer indicator located in front of the radar bearing operator. This

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was the closest approach noted to the use of a combat information center.

Voice tubes and battery-powered phones were available between the radar compartment; the bridge and gunnery plot. Of these, the voice tube was considered the primary means of communication. The only means of communication between the fire control and air search radar compartments was the small scuttle shown in Enclosure (A). Figure 10 shows the installation of a gyro repeater on the left with a rough antenna bearing indicator at the right. The voice tube and telephone are shown just above the range indicator. A vernier bearing indicator with a pointer controlled from the bridge was mounted in line and just to the right of the indicators shown. A tabulation of maximum and reliable ranges obtained with range and bearing errors for this type of equipment is given in Table I.

The operation of the air search radars was handled in much the same manner as the fire control radar. The Type 3 Mark 1 Model 3 equipments required two operators with three additional men for the intercept receiver and the phones. The radar technical officer would assist in either the surface search or air search compartments depending on the tactical situation. Figure 11 and Enclosure (A) show a typical arrangement of equipment. The bearing indicating dial located on the bulkhead and the mechanical antenna control system shown in Figure 11 are typical.

Both air search equipments were operated during periods of impending raids, but no definite system for correlatating the two sources of information seems to have been in effect. Both equipments furnished their range and bearing information to gunnery plot, the bridge and the gun mounts via voice tube and telephones. While the radars were only operated for short periods the intercept receivers were manned continuously when in a danger area and a great deal of faith was placed in their performance. The average range of the air search radar on a single aircraft was claimed to be 50 km.

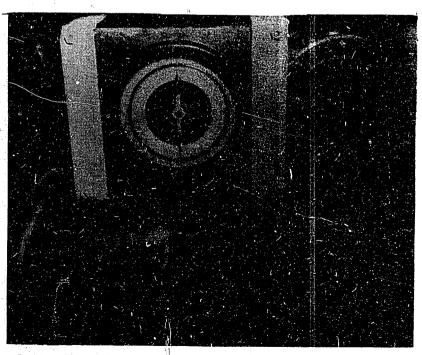


Figure 10

BEARING INDICATOR INSTALLED IN
FIRE CONTROL RADAR COMPARTMENT IN DD HANAZUKI

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Table I
PERFORMANCE DATA OF MARK 2 MODEL 2 RADAR (MAY 1944)

Modif.	Ch. 4 m	Antenna		Rang	;e -	(KM)			erin		Er	Range ror (n	n)
Radar	Ship	Height (m)		вв	CA	DD	SS	Max	Min	Aver	Max	Min	Aver
4	YAMATO (BB)	32.5	Max Aver		17.0	16.0 10.0	7.0	3	0	2	+400	+100	+200
2	MUSASHI (BB)	32	Max Aver	25 20	18 16	12 9	7 6	5	0	2-3	+600	0	+200
2	ATAGO (CA)	20	Max Aver	26 21	20 16	17 10		5	1	3	+700	0	+300
4	MAYA (CA)	19	Max Aver	12 10	12 10	10 8		5	0	2.5	+100	+25	+60
2	HAMANAMI (DD)	18.5	Max Aver	12 10	10 9_	7 5.5	6 4	6	0	.8	+500	0	+50
2	HAYANAMI (DD)	15.6	Max Aver	23 20	19 16	13 11	7 6.5	5	0	1.1	+385	. 0	+120
2	HARUSAME (DD)	15	Max Aver	15 9•5	13 9	9 7	5 5•5	5	0	2	+200	0	+100
2	ASASHIMO (DD)	15	Mex Aver	15 13	13 10	.11 8	6 3•5	8	0	2.6	+600	0	+120
4	TAMANAMI (DD)	16	Max Aver	20 12.5	13.5 8.5	8 6.1		7	3.5	4	-400	-200	-200
2	FUJINAMI (DD)	14	Max Aver	25 19	23 17	14	10 .5	5	1.5	2.1	+500	0	+250

8	Маре	Designation	Object	Resourch	roh	Remarks	Installation	Freq. Wave Fulse Langth	Fulse Output Length (Peak)	Postr Output (Peak)	Hop. Freq.	Oscillation Oscil Circuit Val	Value	Inter. Front	Detector	Detector Oneilator
\mathbf{I}	2 Wb-1		Anti-oir warning	1943-9	1943-9 1944-2	in use	Both sides of	2 8	6	6	500	LG-Girouit	T-311x2	14.5	UII-954	. DK-955
-	Model-3 for ships	+	M141-021		$\overline{}$	2	Mizzen Mast	3	10	ĕ ·	500	LC-Circuit	T-311x2	14.5	UN-954	UN-935
~		Anti-Air	Anti-air warning	1707-7	1,11	11 450			5	5	١.		T-311x2	14.5	UN-954	UI-955
प		rine	Anti-air warning	1943-9	1944-7	In use	on Conning Tower	2 11	10	ī			- /			100
1		13 for small	Anti-sir warning	1943-9	1944-7	in use	Forement .	2 в	10	10	500	LC-Gircuit	T-311x2	14:5	07-954	Ut-933
	Tuna 2 Marks 2		Anti-air warning	1942-1	1942-4	in use	Bridge (Converted	1.5m	10	5	1000	IC-Clrouit	T-310x2	21.5	UN:-954	UK-955
1	Model-1	27 744	Anti-sir warning	1942-8	1942-12	out of use	Fore-top	11.5m	10	5	1000	LC-Circuit	T-310x2	21.5	771-954	UII-955
9		7	Anti-nin warning	1941-5	1	in use	Fore-top	1.5m	10	5	1000	LC-Circuit	T-310x2.	21.5	UN-954	. \$56-ill!
-		C. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1.	and and anti-	10.1	+	out of use	Fore-top	1.5m	01	у	500	1.C-Circuit	T-311x4	51.5	UN-954	UN-955
α	-	Z-18A-12	Surface warning					1	-	5	100	TO Od would	Φ-31114	21.5	UH-954	m-959
9		21-Ke1-4	Anti-sir and Anti-	1944-2	1944-5	stopped	Fore-top	1.50	5	70	1000			3,15	130 10	100.0
片		21-Ka1-5	Anti-air warning and	1944-5	1944-9	not yet used	Fore-top	1.5m	6	30 .	1000	IC-Circuit	T-511X4	3.5	# 475	UN-737
티		38	Anti-surface warning	1945-3	1943-10	-		. 58 cm .	5	2	005	Resonator-tane	SN-7 x2	8.75	2400	מככע-ויוט
4	Type-3 Herk-2	23(38)	Anti-surface fire	1945-10	1944-5	not yet used	Fore-top	58 om	2.5	5	3750	Resonator-tane	T-321	8.75	2400	UN-955B
* :	Model-3	74	Anti-purisoe fire	1945-11		геаневтор		28 om	2	٢	1000	Parellel wire	. ID-212-0x2	15	Crystal	TD-1
:	Model-4	30-761-1	control	_	_	out of use	Fore-or Mizzen	10 0m	TO	500w	2500	Magnetron	K-311	Super	₩-60	
1	Model-2	200	Anti-	4		out of use	Fore-or Mizzen	10 cm		2	2500	Magnetron	и-312	Astodyne	M-60-A	
Ü		2-104-22	And anning				Conning Tower of	10 00	5	2	600	Magnetron	ц- 312-В	14±1	Crystal	E-09-7
16		22-Ka1-3	Anti-suriace warming	1746-14	П	100	Submarine		,	•	3500	Vagnetron	M-412-A	14±1	Crystal	E-09-K
듸		22-Kai-4	Anti-surface warning	1942-12	2 1945-12	in use	Fore-or Mizzen	10 cm.	10	2	. 300	NER HOLLON	20 000		Canada	11 20 0
耳	Prototype Mark-3	220	Anti-surface fire	1944-2		not yet used	Fore Mast and	10 cm	10 .	2	2500	Magnetron		1421	or A contract	1 100-3
म	Prototype Mark-3	105 S1	Anti-surface fire	1944-5	1945-1	research		10 од	IO	^	2000	мадивстоп	L		2	
20	Prototype Mark-5	105 82	Anti-surface fire	1944-2	\neg		ship or Sea Shore	10 cm	- 16	N.	2000	Magnetron	W-246-W	,	.,,,,,,	

		ì																	
101	Logn	7		-	diga hapresensetich	Vuteuo	•			:		1	Ti at anna	AGRUTAGY	Anglo		No. of	Degree of	
ector	tector Oscillator	F	01. 10 au	Somming	18 Scalo	Туре	Geln (4b)	Hor.	Angle Vert	Soale Effective (km)	Distance (km)	Distance of Range (km)	Discrimination of Bearing Discrimination Spare Parts	of Bearing	Disorimination		Operators	Operators Operating Difficulty	Maintenance
1-954	. UN-955	۳	:]	Liner	Heol	2 x 4 Horizontal	12	± 340 ±	± 17.5°	150(300)	٦,	+ 20,3km	3 km	±100	00954		2	None	Pew troubles
1-954	UN-955	~	3	Linear	r Mechanical	Single Vertical	2 3	3600		150(300)	5	± 2w3km) km			î.	2	None	Antonna System
N-954	UH-955	प	75	Linear	r Mechanical	Yagi Hor.	-3	± 300 ±	250	150(300)	5	+ 243km	3km	± 50	2600	Number of Vacuum	2	None	Antenna System
1-954	DN-955	4	73	Linear	r Mechanical	2 x 4 Hor.	12	±3,6€	± 17.50	150(300)	5	± 2~3km	3km	± 50	0090		2	None	Antenna System
11-954	UR-955	5	ě	Linear	r Electric	6 x 2	17.	± 0,11±	400	150	5	± Iveka	→ 2km	± 50	5 20° >	Number of Resistances	N	None	At first trouble Frequently broke down
H-954	EI-955	6	3	Linear	r Electric	4 x 2	- 1	1170	400	150	5	± 1~2/m	v.5)@	± go	5 400		N	Slight	Antenna System
3-954	(fr-95)	7	120	Linear	r Electric	4 1 3 Bor.	- 1	±170 €	300	150	5	± lw2km	12212	± 50	₩20°	Number of Condensers	2		No troubles
N-954	W-755	- 6	25	Linear	r Option1	4 x 3 Hor.	14	±170 ±	30°	270, 14 against	-	± 0.5km	1km	± 1º	90		-		TIBDIO TO DIGHE COMP
1,054	100-944	. 9	120	Linear		4 x 4 Hor.	15	±170 ±	± 17.5°	150, 15 against	5	# 1.0km	1,5km	± 10	æ				TIBUTO TO DIORE HOME
400	Di-9558	10	ě	Linear	r Electric	4 x 4 Hor. Interphenseable	15	±17° E	±17.50	n bettleship	4	± 0.5km	1km =	± 10	80		·	out.	Ordinary
400	W-955B	Ë	120	PATRO 1	Mechanical	Tr: Paraboloid 1'72 dia.	Ħ	±250 ±	± 25°	150, 15 against	1.3	± 2km	Research Incompleted	± 3º	Research Incompleted				Tieble to breek down
rystal		12	75	Warning:	ng: Linear Range earing: Sinusoidal	Tr: Paraboloid 1.7m dia.	==	±250	250	33, 22 against	1	± 50m	150km	±0.5°	140		,		Come some trouble
6	$^{-}$	-13	7	Logar	Logarithmio Electric	Tr: Paraboloid 2m dia. Rec. 2mDouble Ant. (Bwitch)	6T 6T	∓ 06 ∓	90	40, 11 against	144	± 50m	150 ш	±0.50	140		,		Care some trouble
A-09		- 4	120	Linear	r Electric	Paraboloid 0.8 x 117m		∓ 250 ∓	∓ 12º	60, 30 against	1.5	± 500m	1.5)cm	± 3º	×±300		J	ale ,	Caro some trouble
rystal	E-09-7	-5	995	Linear	r Electric	Hona 400mm	13	± 190 ±	± 19º	60, 22 against	1.5	± 500m	1.5km	o£ ∓.	\$5 ±400			16	Cuto some atomore
rystal		16	75	Linear	н	Horn 400mm	13	±19° #	190	60, 10 egainet	1.5	± 500m	1.5km	# %	5 ± 400	Number of Resistances in use x 1/10	ů		Mo elonoto
rystal	+	.17	15	Linear	r Electric	Horn 400mm	13	±190 ±	190	60, 25 against	1.5	±100~250m	1.5km	0€ ∓	\ ~*±40° }	Number of Vecuum Tubes in use x 4	3		No exonore
rystal		18	3	Warning:	ng: Linear, Range	Paraboloid	25	H 70 H	70	60, 35 against	1.5	±100~250m	1.5km	±40°	₩±130	Number of Magnetron	3-4	Slight	No trouble
rystal	_	19	75	Warning:	farning: Linear, Range	Horn,	15	±150 #	± 150	60, 28 sgainst	1.5	1100~250m	1.5km	±300	20€±300	•	*		No trouste
		~ 24,	75	Werni and B	Worning: Linear, Range and Bearing: Sinusoidal	Hozh,	158	## 2055 ##	8 8 1 1 H	60, 30 against	1,5	±100~250m	1.5km	±30°	%±300)			None	No exonote
				j															

SHIPBORNE	
E RADAR COUR	TABLE III
NTERMEASURES	H

		0						
7 Spherical Antenna		6 Wark-49 Antenna	S 0 - antenna	d Wetox-antenna	3 Racket-antenna	2 Radar Counter Neasure Model-3	1 Radar Counter Weasure Kai 3	No. Name Opsign
							E 27	Desig- nation
RCM FOR CM-Wave		ROW for cm-wave	RCW for meter-wave	ROW for meter-wave	RCM for meter-wave	RCM for cm-wave	RCW for meter-wave	Object
3/40		6/44	6/4	6/43	6/43	1/44	6/43	Research Started Fi
0.00 No.	- 1	12/44 In	12/44 No	12/44 In	12/44 In	4/44 11	4/4.4	3.0
used	1	In use	Not yet used	In use	In use	la use	In use	Remarks
oditate and odbuding the Louis	Sind and Submarine of and	Surface and Submarine, Land	Surface and Submarine	Surface and Submarine	Surface and Submarine	Surface and Submarine (Land)	Surface Ships and Submarines	Installation
	0 /S=0 0 ==	0. 80 m20.03m	4mY.75m	4m\S.75m	4mY.75m	400mc=19,000mc (0.75n=0.03m)	7.5mc=400mc (4m=0.75m)	Frequency Band (Wave tength)
		Ŧ				Crystal Detecto	Single Tuning Superheterodyne	Туре
	Receiver Used, Hodel - 3	Receiver Used, Model-3	Receiver Used, Kai-3 (E-27)	Receiver Used, Kai-3 (E-27)	Receiver Used, Kai-3 [E-27]	,	Parallel Wire Single Tuning	Receiver Local Oscillator
	1-3	/J	3 (E-27)	3 (E-27)	3 (E-27)	17.5 ± 3.5mc UZ-6C6x4	14.5mc Un-955x3 UZ-6C6x9	to termediate Tubes Frequency
,				-		6x4 119db	5x3 / 10db	es Gain
		1 2 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	Section of the Control of the Contro			Aural: For Directional and Repetition Frequency	Aural Visual: For Directional and Repetition Frequency	Type of Indication
	Fixed	Portable	Fixed	Fixed	Rotating, Fixed	Directional: Parabolic Disc T All-around: Spherical-antenna	Directional: Rack All-around: Wetox	Type
	All-around	Directional	All-around	All-around	Directional II	Directional: Parabolic Disc Type (Wark-49) (Portible) All-around: Sphericak-antenna	Directional: Racket-antenna (Rotating Fixed for Surface craft). All-around: Welox-antenna or B - antenna	Kind
	-20db	+5 <i>db</i>	-6 <i>ab</i>	-6db	-346	(-B) (Port	Fixed for	Antenna Gain
	٠ ٠	10°00° 10°00°		- 10 mm	30°50° 30°00°	ble)	Surface craft).	Beam Angle Horizontal Vertical
	n			53				
		•	F			Numb	Num	
						Number of Vacuum Tubes in Use x3	Number of Vacuum Tubes in Use x3 Few Replacement Parts	Spare Parts
	None	Slightly Difficult aboard Subs	None	None	None	One None	One	No. of Degree of Oper- Oper- ators ating Difficulty
	No trouble	No trouble	No trouble	Liable to Insulation Breakdown	Liable to Insulation Breakdown	No trouble	No trouble	Ma in tenance
Ļ	7	9,	ა	_	L _U	^	Ŀ	<i>№</i>

RESTRICTED

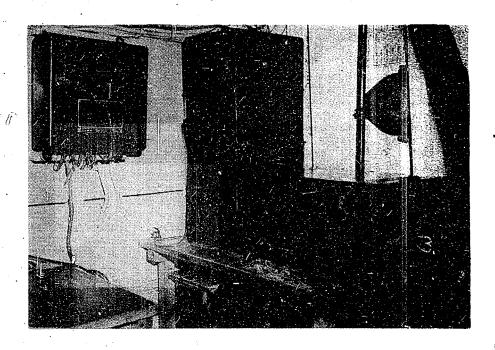


Figure 11

TYPE 3 MARK 1 MODEL 3 RADAR

INSTALLATION IN DD HANAZUKI

Part V TECHNICAL DATA ON EQUIPMENT

A. General

Table II lists the types of radar equipment in use at the end of the war and their characteristics as well as equipment under development. Only radars in use by the fleet will be discussed in this report and reference is made to the report on experimental radars for data on the other equipments. (NavTechJap Report, "Japanese Experimental Radar", Index No. E-12.)

All equipments in use by the Japanese Navy at the end of the war may be considered obsolete by U.S. Navy standards. The only scope presentation in use was the standard "A" scan with linear and sinusoidal sweeps. Methods of reading ranges varied from mechanical scales to phase shifters and electronic range markers.

The Type 3 Mark 1 Model 3 (13) and the Type 2 Mark 2 Model 1 (21) equipments were the only air search radars in use. The Mark 2 Model 2, 10 centimeter equipments had two modifications in use at the time of the surrender. The Modification 3 radar was installed in submarines for surface search. Modification 417 for surface search and Modification 45 for surface search and fire control were installed in surface vessels.

Table III lists all RCM equipments in use and under development at the end of the war. Both the meter wave (E27) and the centimeter wave (Model 3) receiss were installed in practically all combatant vessels. No electronic jamming equipment was installed or under development for naval vessels.

B. Air Search Radars

1. Type 3 Mark 1 Model 3 (13) Radar

This equipment was adapted for shipboard use from a landbased equipment of the same designation. The only modification accomplished for the shipboard installation was in the antenna and antenna control system. While surface vessels used the same antenna as in the landbased equipment, a special vertical dipole and a YAGI antenna were used in submarines. Examples of shipboard antennas may be seen in Figures 5 and 7. In addition to the mechanical antenna train used on land, a number of the shipboard installations had electrical training systems. This 150 megacycle equipment was very compact and simple in design and operation. Compared with other shipboard radars, it gave very little trouble. The simplicity of the equipment is shown in the block diagram contained in Figure 12.

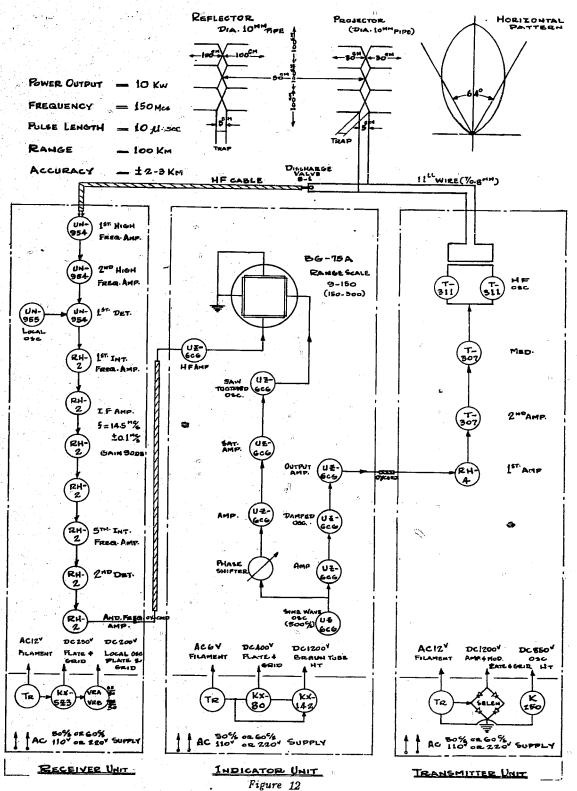
The transmitter developed a peak power output of 10 kilowatts with two type T-311 tubes connected in a 2C oscillation circuit. A plate voltage of 8000 volts and a grid bias of - 1300 volts was used. The modulater tube (P-560) reduced the bias to zero during oscillation. The pulse rate was 500 per second and the pulse length 10 micro seconds. The receiver and indicator were also of conventional design. The characteristics are completely listed in Table II and complete wiring diagrams are included in Enclosure (E). Instruction books (NavTechJap Document Nos. ND21-6085 and ND21-6086) have been forwarded to WDC. A sample of this equipment was obtained and shipping data is given in NavTechJap Report, "Japanese Electronics - General", Index No. E-28.

2. Type 2 Mark 2 Model 1 (21) Radar

This radar was designed especially for shipboard use. While two subsequent modification were produced with three more under development, the equipment that reached the fleet was never considered equal in reliability and performance to the simple Type 3 Mark 1 Model 3. The trouble was claimed to have been largely due to poor receiver sensitivity that resulted from using acorn tubes as RF Amplifiers at 200 megacycles. The same receiver design was used in all modifications despite adverse service reports. A block diagram is included as Figure 13 and complete wiring diagrams are given in Enclosure (F). The first model of this equipment had a peak power output of 5 kilowatts with a 10 microsecond pulse length and a pulse rate of 1000 per second. The transmitter oscillator utilized two type T-310 tubes in a conventional L-C circuit. A single mattress type antenna was used for transmitting and receiving.

The first modification merely replaced the single antenna with an antenna having two horizontal sets of four elements each for transmitting and two horizontal sets of three elements each for receiving. The second modification replaced the antennas with another single antenna which consisted of three horizontal sets of four elements each.

The third modification was undertaken to adapt the equipment to both air and surface search. The frequency was left at 200 megacycles but the power was increased to 30 kilowatts with a choice of either 6 or 10 microsecond pulses. The pulse rate was reduced to 500 per second. The antenna was to be the same as that used on the Modification 2 except for the addition of lobe switching. Modification 4 and 5 were to accomplish only small changes such as pulse lengths and rates. No installations of Modification 3 and later equipments had been completed at the time of surrender.



BLOCK DIAGRAM FOR TYPE 3 MARK 1 MODEL 3 RADAR FOR LAND, SHIP AND SUBMARINE USE

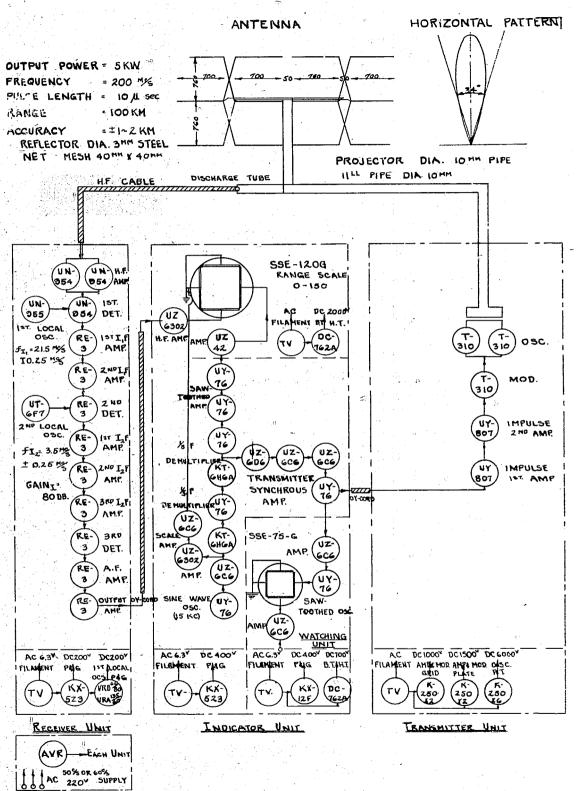


Figure 13
BLOCK DIAGRAM FOR TYPE 2 MARK 2 MODEL 1 RADAR

C. Surface Search and Fire Control Radars

1. Mark 2 Model 2 Modification 4 Radar

Figure 14 shows a block diagram of this equipment. Complete characteristics may be obtained from Table II, while a complete set of wiring diagram is included in Enclosure (G). This 10 centimeter wave equipment was installed in all combatant vessels as either a surface search equipment (Modification 4M) or a combination surface search and fire control equipment (Modification 4S). Larger electro-magnetic horns, a selsyn antenna control system, and additional voltage stabilizers were used in the latter type installations.

This equipment used a water-cooled Type M-312-A magnetron whose filament was made of pure tungsten. The ratings of the tube are as follows:

Filament	10 volts, 19.5 amperes, 195 watts
Total anode voltage	
Magnetic field	700 gunses
Antenna output power	2 kilowatt peak
Allowable temperature of anode	60° centigrade
Oscillation wave length	sapation

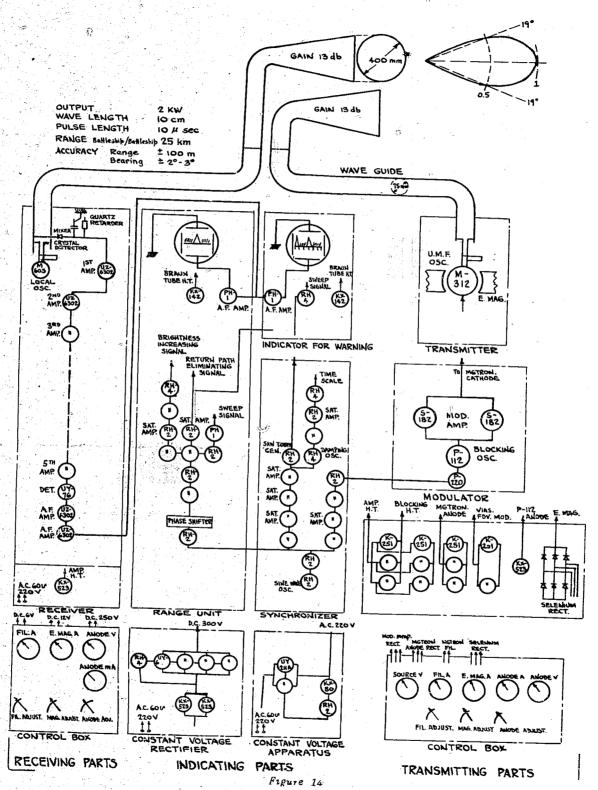
The plate voltage was 7,000 volts constantly impressed on the anode with a negative pulse of about 5,500 volts applied to the cathode by the modulator. The output of the magnetron was fed through a single tuning stub to a radiation element located in the mouth of the wave guide.

The receiver utilized a superhetrodyne circuit with a crystal detector and a Type M-60-S magnetron as local oscillator. Range tuning was accomplished by varying the field current and fine tuning by charging the cathode voltage of the magnetron. There were five stages of intermediate frequency amplification which were tuned to 14.5 megacycles with a 2 megacycle bandpass. A Type OY 76 tube was used on the second detector with two stages of amplification following. All amplifying stages used the Type UZ 6302 tube. A quartz crystal "retarder" was connected in paralled with the input circuit to the first intermediate frequency stage to produce a delayed pulse for tuning. The total gain of the receiver was claimed to be 120 decibles.

A tuning fork and two Type RH-2 tubes used as an oscillator and a buffer were to supply a constant frequency sine wave of 2.5 kilocycles to the synchronizing circuit, a sweep circuit, and to a phase shifter circuit in the range unit. The synchronizing circuit transformed the sine wave into a negative 120 volt pulse which triggered the modulator. The sweep circuit generated the indicator sweep voltage and a 30 kilocycle electronic range scale. The sinusoidal output of the tuning fork oscillator was also squared up in the phase shifter circuit and used as intensifying pulse for the cathode ray tube.

The other circuits used in this type equipment are considered conventional and specific details may be obtained on all components from the wiring diagrams in Enclosure (H).

The antenna consisted of two electromagnetic horns mounted one above the other. (See Figure 5 for a typical installation.) The upper horn was used for receiving and the lower one for transmission. The gain of the Modification LS antenna was said to be 13 decibles. Samples of this equipment have been collected and shipping data may be obtained from Nav-TechJap Report, "Japanese Electronics - General", Index No. E-28.



BLOCK DIAGRAM OF MARK 2 MODEL 2 MODIFICATION 4 RADAR

E-01 RESTRICTED

2. Mark 2 Model 2 Modification 3 Radar

This equipment was specially designed for submarines and installed only on them. Electrically it was similar to the Modification 4 equipment, but the mechanical construction was much more compact. Some electrical differences existed in the transmitter, the RF system, the antenna, and the pulse rate, which was only 600 per second. Complete characteristics are contained in Table II and complete wiring diagrams are included in Enclosure (H).

This equipment used a single horn antenna for both transmitting and receiving. The wave guide water seal is described in the installation section of this report. The unusual duplexor and RF system used with this equipment produced a circularly polarized wave, which are detailed in NavTechJap Report, Index No. E-20. The transmitter modulating pulse was also applied to the second of two duplexor tubes used in the deplexor assembly to help protect the receiver crystal. It was found necessary to reduce the fixed transmitter magnetron voltage from 7000 to approximately 5000 volts and to increase the negative modulating voltage accordingly. The noise produced with the higher voltage on the anode blocked the receiver when used with a common transmitting and receiving antenna. A sample of this equipment has been obtained and shipping data may be obtained from NavTechJap Report, Index No. E-28.

D. Radar Countermeasures Equipment

Table III lists the characteristics of the two intercept receivers and their antennas. Wiring diagrams and an instruction book for the Model 3 receiver are contained in NavTechJap Document No. ND22-3007. Wiring diagrams for the Modification 3 (E27) receiver are included in NavTechJap Document No. ND21-6154. Additional information on the antenna designs used may be obtained from NavTechJap Report, "Japanese Antennae". Index No. E-16. Samples of these equipments have been collected and shipping data may be obtained from NavTech-Jap Report, Index No. E-28.



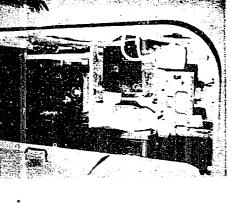
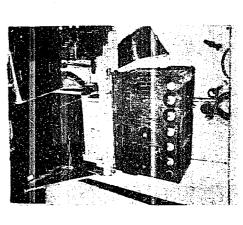


FIGURE 1(A)



PHOTOGRAPHS OF MARK 2 MODEL 2
MODIFICATION 4S AND TYPE 3 MARK 1
MODIFICATION 3 RADAR INSTALLATION
ON DD HANAZUKI

FIGURE 2(A)



ENCLOSURE (A)

FIGURE 3(A)

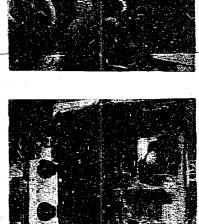


FIGURE 4(A)



FIGURE 5(A)

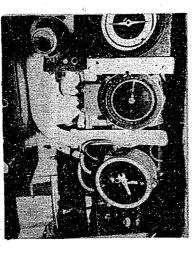


FIGURE S(A)

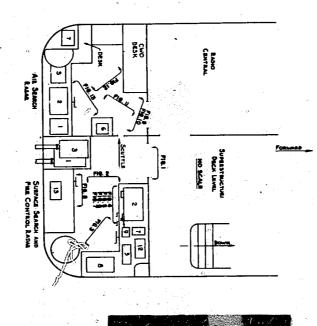


FIGURE 7(A)



FIGURE 8(A)



FIGURE 9(A)

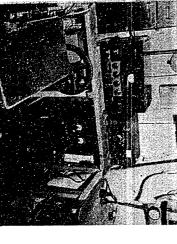


FIGURE 10(A)

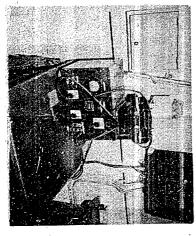


FIGURE 11(A)

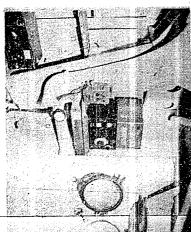


FIGURE 12(A)

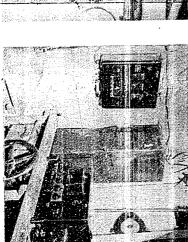


FIGURE 13(A)



FIGURE 1(B)

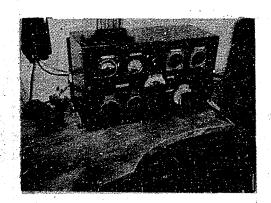


FIGURE 2(B)

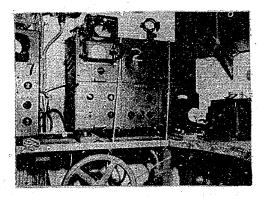
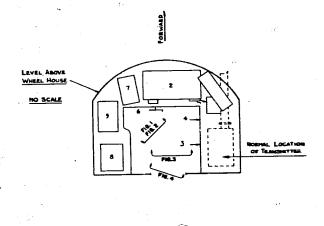


FIGURE 3(B)

ENCLOSURE (B)

, PHOTOGRAPHS OF MARK 2 MODEL 2 MODIFICATION 4 RADAR INSTALLATION ON CV KATSURAGI



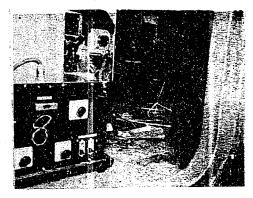
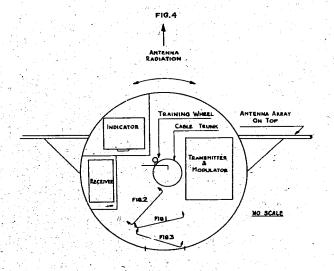


FIGURE 4(B)

ENCLOSURE (C)

PHOTOGRAPHS OF TYPE 2 MARK 2 MODEL 1
MODIFICATION 3 RADAR INSTALLATION
ON CV KATSURAGI



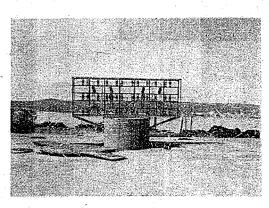


FIGURE 4(C)

COMPLETE UNIT RETRACTABLE INTO FLIGHT DECK

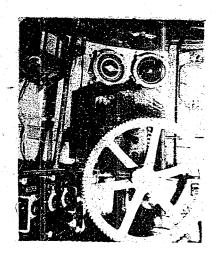


FIGURE 1(C)

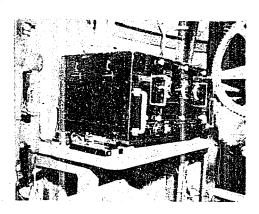


FIGURE 2(C)



FIGURE 3(C)



FIGURE 1(D)

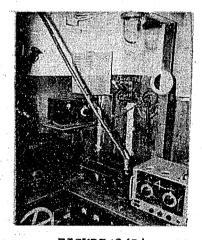


FIGURE 2(D)

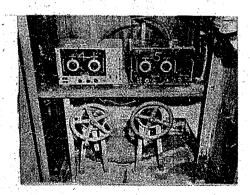
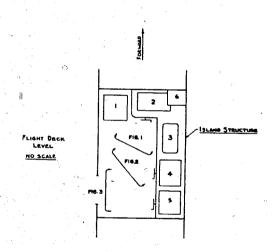


FIGURE 3(D)

ENCLOSURE (D)

PHOTOGRAPHS OF TYPE 3 MARK 1
RADAR INSTALLATION ON CV KATSUR



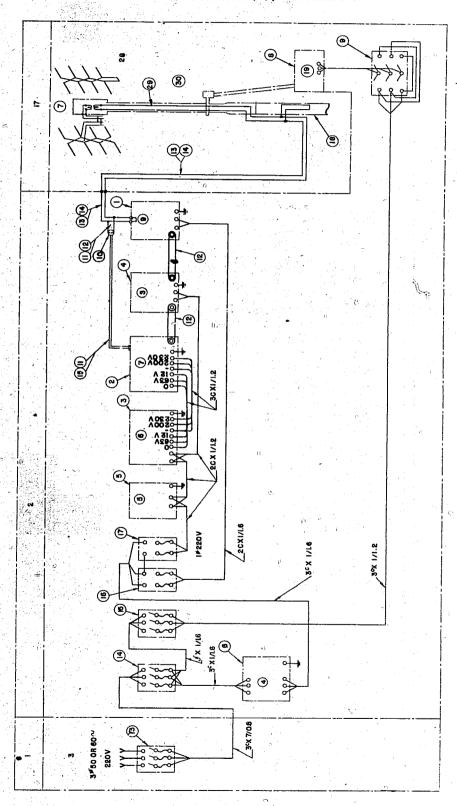
ENCLOSURE (E)

WIRING DIAGRAMS OF TYPE 3 MARK 1 MODEL 3 RADAR

LIST OF DIAGRAMS

Overall Hook-up Diagram	Page	32
Exterior View of Transmitter	Page	34
Transmitter Connection Diagram	Page	35
Receiver Wiring Diagram		39
Wiring Diagram of Receiver Rectifier (Old type)	rage	42
Wiring Diagram of Receiver Rectifier (New type)	Page	44
Schematic Diagram of Indicator (C-Model 1)	Page	45
Construction of the Antenna		51
Antenna Directivity Pattern	Page	52
Schematic Diagram of Antenna		53
Radiator Matching Lines		54
Reflector Matching Lines		54
Feeder Line Watching		55
Receiving Circuit Branching Points		

ENCLOSURE (E), continued



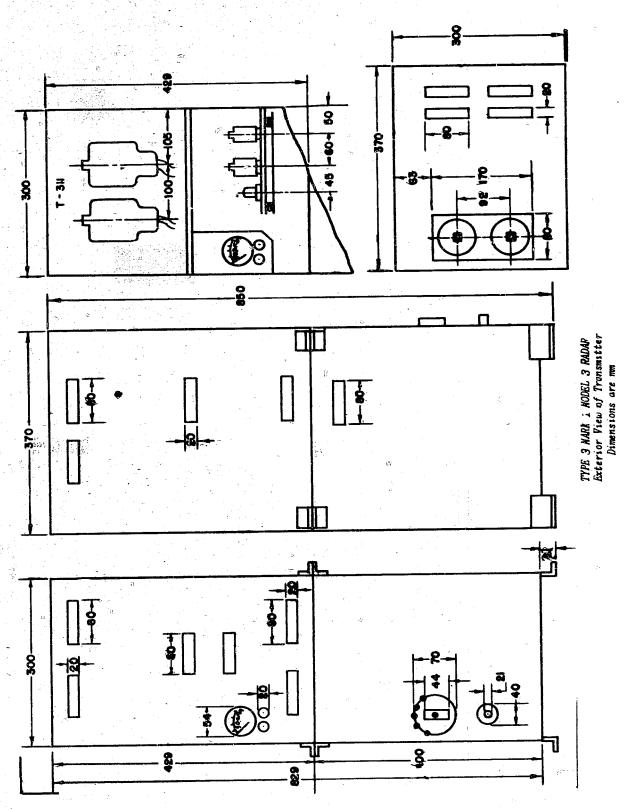
TYPE 3 MARK 1. MODEL 3 RADAR Overall Hook-Up Diagram

ENCLOSURE (E), continued

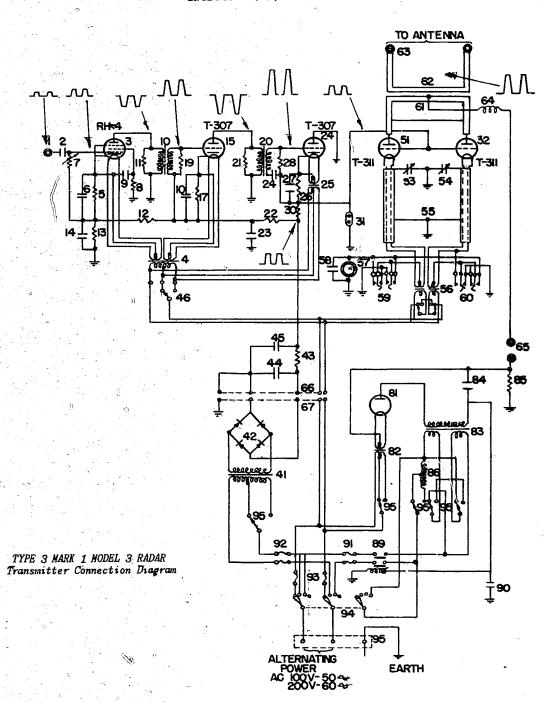
LIST OF PARTS USED IN TYPE 3 MARK 1 MODEL 3 - OVERALL CIRCUIT DIAGRAM

Number	<u>Item</u>	Number	<u> Item</u>
1	Power room	17	Antenna
2	Radar room	18	Antenna for ship
3	Power room (shipboard)	19	Antenna rotating mechanism
4	Automatic voltage regulator	20	Fixed with a g h.p. electric motor
5 6-	Wave meter Rectifier for receiving set	21	Reversible switch (controller form)
7	Receiving set	22	Cord
8	Indicator	23	Tripod circuit switch breaker
9	Transmitter	24	Double pole switch
10	Special discharge tube	25	Wooden pole
11	Conductor is 4mm in diameter	26	The rest
12	Interval of two lines is 23mm	27	Radiator
13	Conductor is 4mm in diameter	28	Reflector
14	Two lines is 50mm in interval	29	Outer pipe of 150mm inside dia-
15	High frequency cable		Conductor of 4mm diameter Two lines of 60mm interval
16	HADO = peak of a wave or surge or undutate resistance 230	30	Conductor of 2.4mm diameter (7/0g) or two lines of 30mm interval

ENCLOSURE (E), continued



ENCLOSURE (E), continued

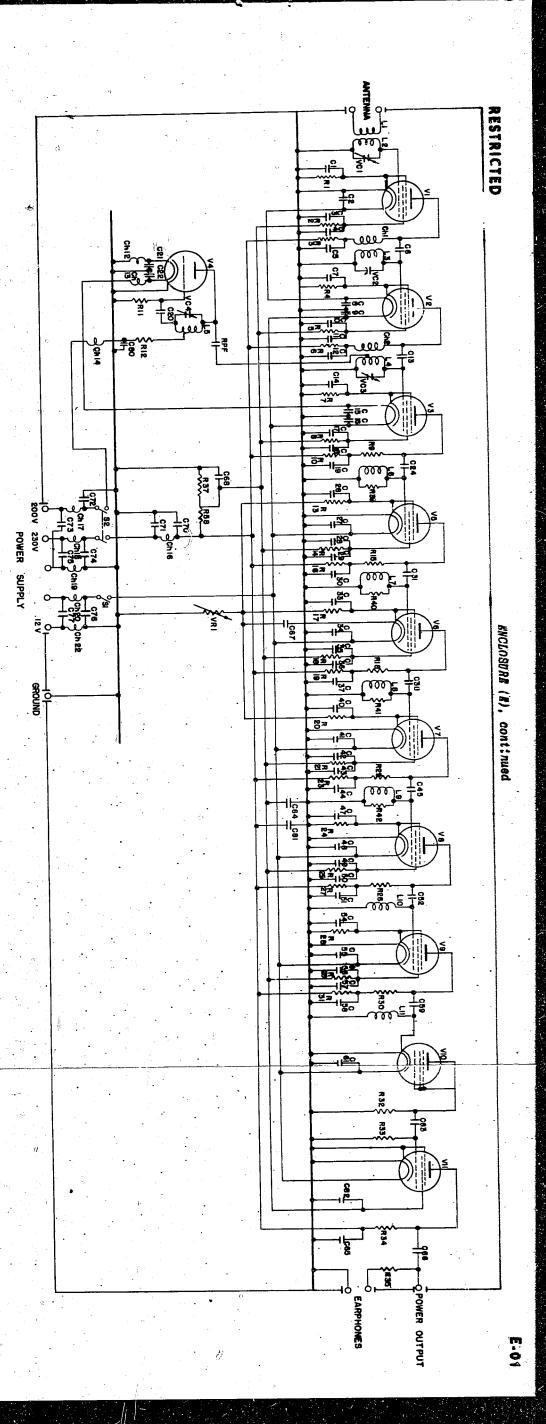


LIST OF PARTS USED IN TYPE 3 MARK 1 MODEL 3 RADAR TRANSMITTER CONNECTION DIAGRAM

		- · · · · · · · · · · · · · · · · · · ·	
Number	<u>Item</u>	Model & Type	Note
1	Input terminal	Naval service type	Single pole plug
2	Connection condenser	Mica	10,000 μ _μ F
3	First amplifying tube	RH-4	l'
4	Filament heat transformer (bias)	e de la companya de La companya de la co	9 VA 220 110/12V 12V
5	Cathode inclination resistance	C-2	10 KΩ
6	Cathode by-pass condenser	OP-654	2FF 1000V (oil impregnated paper)
7	Control grid resistence	NV-200-S	50 K Ω
8	Screen grid resistence	C-2	200 K Ω
9	Screen by-pass condenser	OP-652	1 μ F 1000V (oil impregnated paper)
10	Output transformer	TF Model I	300 T = 300 T
11	Wing resistance	C-2	10 ΚΩ
12	Voltage drop resistance	C-5	200 Κ Ω
13	Voltage drop resistance	C-3	100 ΚΩ
14	Voltage by-pass transformer	OP-654	$2~\mu extsf{F}~1000 extsf{V}$ (oil impregnated paper)
15	Second amplifying tube	T-307	
17	Cathode inclination resistance	0-2	10 ΚΩ
18	Cathode by-pass condenser	OP-656	$2 \mu F$ 3000V (oil impregnated paper)
19	Control grid resistance	C-2	10 ΚΩ
20	Output transformer	TF Model I	300 T = 300 T
21	Wing resistance	C-2	io κυ
22	Voltage drop resistance	C-5	30 KΩ
23	Voltage by-pass condenser	OP-65 6	2 μ F 3000V(oil impregnated paper)
24	Modulator	T-307	4.
25	Filament amplifying tube		6 VA 220 110/12V

Number	Item	Model & Type	Note
26	Cathode inclination resistance	C-2	20 ΚΩ
27	Cathode by-pass condenser	OP-656	$2~\mu F$ 3000V (oil impregnated paper)
28	Control grid resistance	C-2	10 KU
29	Direct current prevention condenser	OP-658	0.1 \(\mu \mathbf{F}\) 3000V (oil impregnated paper)
30	Grid series resistance	C-2	20 ΚΩ
31	Glow tube	4	
41	Power transformer		· · · · · · · · · · · · · · · · · · ·
42	Serenium rectifier		
43	Smooth resistance	C-2	
44	Smooth condenser	OP-656	$2 \mu F_3000V$ (oil impregnated paper)
45	Smooth condenser	OP-656	2 μ F 3000V (oil impregnated paper)
46	Power switch		
51	Oscillating tube	T-311	
52	Oscillating tube		1
<i>5</i> 3	Filament by-pass condenser		
54	Filament by-pass condenser		
55	Filament closed circuit coil		
56	Filament heating transformer	• · · · · · · · · · · · · · · · · · · ·	156 VA105 105/12V 12V
57	Wing ammeter	Service type Model 7	D.C. 50MA
58	Wing by-pass condenser	D-1250	1000 μ F (porcelain)
59	Wing switch	No. 92	A
60	Wing switch	No. 92	A
61	Wing closed circuit coil		
62	Antenna connection coil		
63	Antenna terminal		included in No. 62
64	High frequency choke coil		
65	High pressure terminal		

Number	<u>Item</u>	Model & Type	Note
66	Connection terminal board		en e
67	Connection terminal board		
81	Wing power rectifier tube		
82	Filament heating transformer		18 VA 220 110/5V
83	Power transformer		500 VA 110 110/7000V
84	Smooth condenser	OP-606	0.5 μ F 20 KV (oil pregnated paper)
85	Load resistance	C-5	1 M O x 6
86	Inductive coil		0.015H, 0.06H
87	(Absent)		•
88	(Absent)		
89	Overload relay		
90	Overload by-pass condenser	OP-655	1 μ F 3000V (oil pregnated paper)
91	Safty fuse	e e e e e e e e e e e e e e e e e e e	Electric service type No. 302 Model II
92	Safty fuse		Electric service type No. 302 Model II
94	Power off-on switch	4	
95	Terminal board	-	



ENCLOSURE (E), continued

		THE PERSON NAMED IN COLUMN 1975	•		TION TO THE		The state of the s	ひょうせい アスティ	DT 4 OD 41'
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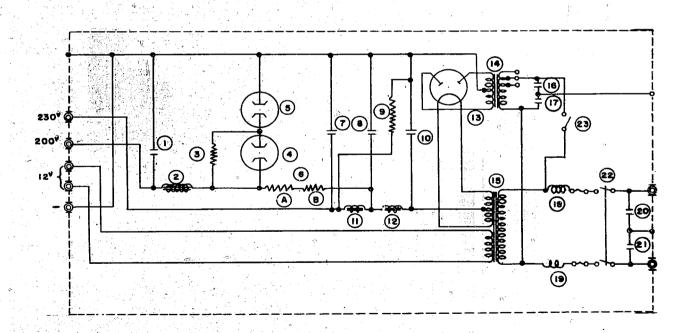
	ignation	Rating	<u>Model</u>	Designation	Rating	<u>Model</u>
	Cl	100 PF ±10%	B-12	C31	50 PF ±10%	B-12
•	C2	0.01 µF ±20%	2	033	0.01 µF ±20%	2
	C3	0.01 μF ±20%	. 2	034	0.01 µF ±20%	2
	C4	0.5 HF ±20%	Mark Ro	035	0.01 µF ±20%	2
-	C5 .	0.01 µF ±20%	2	036	0.5 μF ±20%	Mark Ro
	C6	50 PF ±10%	B-12	C37	0.01 μF ±20%	2
	C7	100 PF ±10%	B-12	C38	50 PF ±10%	B-12
	C8	0.01 μF ±20%	; 2 , 5, 4, 5	C40	0.01 μF ±20%	2
.•	C9	0.01 µF ±20%	2	C41	0.01 μF ±20%	2
	C10	0.01 μF ±20%	2	C42	0.01 μF ±20%	2
	Çll	0.5 μF ±20%	Mark Ro	C43	0.5 μ F ±20%	Mark Ro
	Cl2	0.01 µF ±20%	2:	C44	0.01 µF ±20%	2
	C13	50 PF ±10%	B-12	C45	50 PF ±10%	B-12
٠.	C14	100 PF ±10%	B-12	C47	0.01 µF ±20%	2,
	C15	0.01 μF ±20%	2	C48	0.01 μF ±20%	2
., ·	C16	0.01 µF ±20%	2	°C49	0.01 µF ±20%	2
•	C17	0.01 μF ±20%	2	C50	0 5 5 μF ±20%	Mark Ro
	C18	0.5 μF ±20%	Mark Ro	C51	0.01 μF ±20%	2
	C19	0.01 µF ±20%	2	052	50 PH ±10%	B-12
	C20	10 PF ±10%	B-10	C54	0.01 μF ±20%	2
	C21	0.01 µF ±20%	2	C55	0.01 μF ±20%	2
	C22	0.01 µF ±20%	2	056	0.01 μF ±20%	2
7	C23	2 PF ±10%	Pz-10	C57	0.5 μF ±20%	Mark Ro
	C24	50 PF ±10%	B-12	058	0.01 μF ±20%	2
	C26	0.01 µF ±20%	2	C 59	50 PF ±10%	B-12
•	C27	0.01 μF ±20%	2	C61	0.01 μF ±20%	. 2
	C28	0.01 μF ±20%	2	C63	0.5 μF ±20%	Mark Ro
	C29	0.5 μF ±20%	Mark Ro	C6 4	0.01 μF ±20%	2
•	C30	0.01 µF ±20%	2	C65	4 μF ±20%	Mark I

ENCLOSURE (E), continued

Designation	Rating	Model .	Designation	Rating	Model
c6 6	0.5 µF ±20%	Mark Ro	R16	2 KN ±10%	D-0.25
C67	4 μF ±20%	Mark I	R17	0.3 KN ±10%	D-0.25
C68	0.5 μF ±20%	Mark Ro	R18	10 KΩ ±10%	D-1
C70	0.01 µF ±20%	2	R19	2 KΩ ±10%	D-0.25
C71	0.01 µF ±20%	2	R20	0.3 KΩ ±10%	D-0.25
072	0.01 µF ±20%	2	R21	2 Kn ±10%	D -0 .25
C73	0.01 µF ±20%	2 1	R22	10 KΩ ±10%	D-1
C74	0.01 µF ±20%	2	R23	2 KΩ ±10%	D-0.25
C75	0.01 µF ±20%	2	R24	0.3 KΩ ±10%	D-0.25
C76	0.01 µF ±20%	2	R25	2 KΩ ±10%	D-0.25
C77	0.01 #F ±20%	2	R26	10 Kn ±10%	D-1
C80	0.01 #F ±20%	2	R27	2 Kn ±10%	D-0.25
C81	0.01 µF ±20%	2	R28	0.3 KΩ ±10%	D-0.25
082	0.01 µF ±20%	2	R29	2 KΩ ±10%	D-0.25
R1	0.5 KΩ ±10%	D-0.25	R30	10 KΩ ±10%	D-1
R2	2 K ^Ω ±10%	D-0.25	R31	2 KΩ ±10%	D-0.25
R3	S KU +10%	D-0.25	R32	10 KΩ ±10%	D-1
R4	0.5 KΩ ±10%	D-0.25	R33	100 KU +10%	D-0.25
R5	2 KΩ ±10%	D-0,25	R34	2 KO ±10%	D-2
R6	2 KΩ ±10%	D-0.25	R35	50 Kn ±10%	D-1
R7	1 K 0 ±10%	D-0.25	R36	2 Kn +10%	D-0.25
Rø	2 KO ±10%	D-0.25	R37	5 KΩ ±10%	20 W
R9	10 KΩ ±10%	D-1	R38	5 KΩ ±10%	20 W
R10	2 KΩ ±10%	D- 0.25	R39	30 KΩ ±10%	D-0.25
Rll	50 KΩ ±10%	D-0.25	R40	30 KΩ ±10%	D-0.25
R12	2 KO ±10%	D-0.25	R41	30 KΩ ±10%	D-0.25
R13	0.3 KΩ ±10%	D-0.25	R42	30 KΩ ±10%	D-0.25
R14	2 KΩ ±10%	D-0.25	. S1	T-Type Snap St	vitch
R15	10 KΩ ±10%	D-1	S2	T-Type Snap St	vitch

ENCLOSURE (E), continued

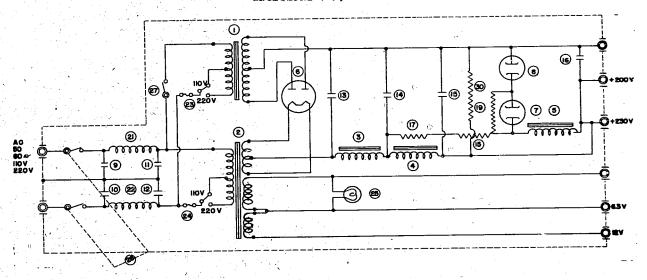
Designation	Rating Model	<u>Designation</u>	Rating	Model
V1 •	UN - 954	₹9	RH - 2	
V 2	UN - 954	٧10	RH - 2	
V 3	UN - 954	V11	RH - 2	
V 4	UN - 955	VCl	PF ±15%	
V 5	RH - 2	VC2	PF ±15%	
⊽ 6	RH - 2	VC3	PF ±15%	
٧7	RH - 2	VC4	PF ±1.5%	
V8 //	RH - 2	VR1	5 Kn ±20%	NV35c



TYPE 3 MARK 1 MODEL 3 RADAR Wiring Diagram of Receiver Rectifier (Old Type)

LIST OF PARTS USED IN TYPE 3 MARK 1 MODEL 3 RADAR WIRING DIAGRAM OF RECEIVER RECTIFIER (OLD TYPE)

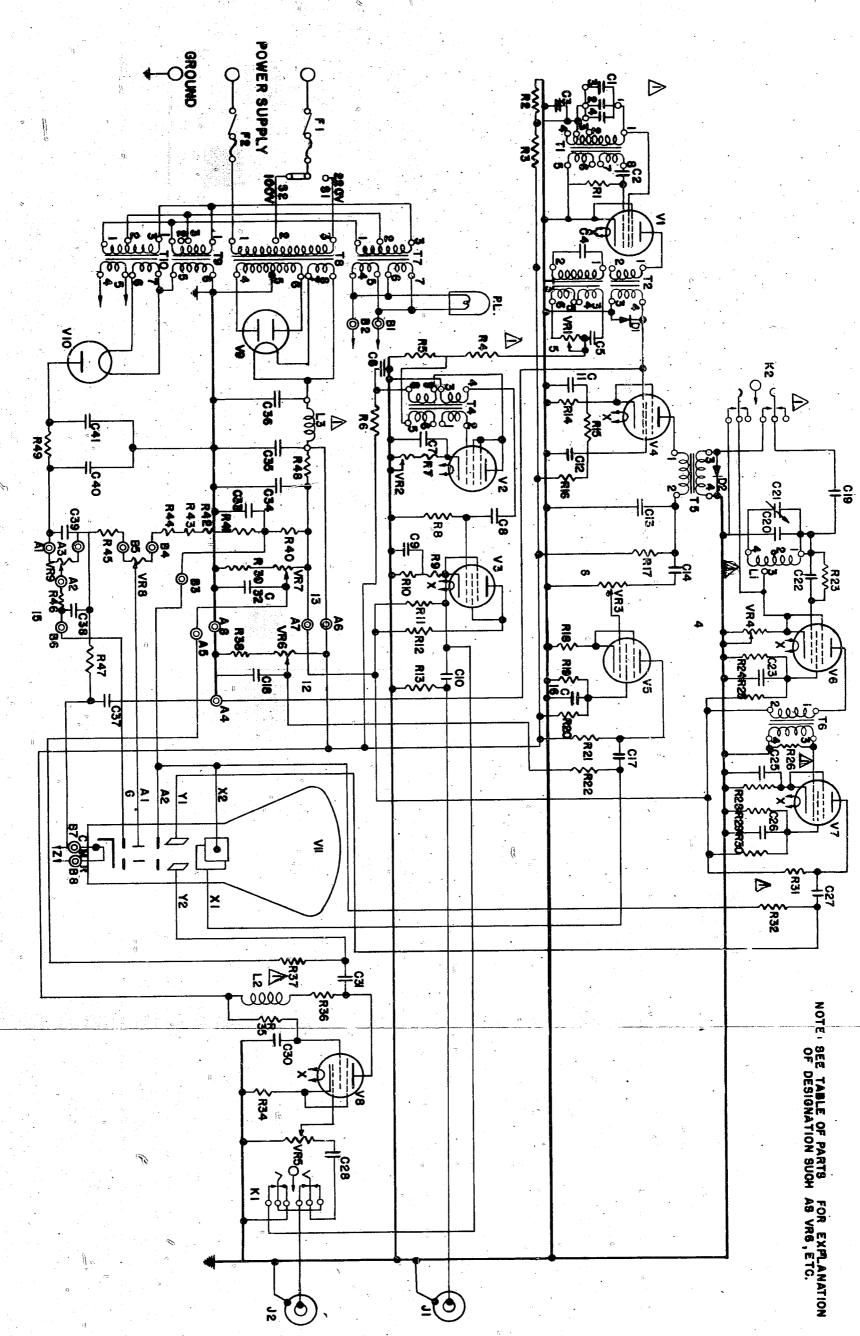
lumber	Item •
. 1	Condenser with magnetic terminals
2	Choke coil
3	Resistor
4	Constant voltage discharge tube
5	Constant voltage discharge tube
6	Resistor
7	Condenser
8	Condenser
9	Resistor
10	Condenser
11	Choke coil
12	Choke coil
13	Rectifier
14	Transformer (for the use of low tension)
15	Transformer (for the use of high tension)
16	By-pass condenser
17	By-pass condenser
18	High frequency choke coil
19	High frequency choke coil
20	By-pass condenser
27.	By-pass condenser
22	Filament circuit breaker
23	Vane circuit breaker



TYRE 3 MARK 1 NODEL 3 RADAR
Wiring Diagram of Receiver Rectifier (New Type)

LIST OF PARTS USED IN TYPE 3 MARK 1 MOLEI 3 RADAR WIRING DIAGRAM OF RECEIVER RECTIFIER (NEW TYPE)

Number	<u>Item</u>
1 - 2	Power supply transformer
3 - 5	Low frequency choke coil
6	Vacuum tube
7 - 8	Low-voltage discharge tube
9 - 12	Mica condenser (Naval standard, type Z)
13 - 16	Paper condenser (Naval standard, type C-1)
17 - 18	Fixed resistance (Type 15 HC HINOMOTO-form)
19 - 20	Fixed resistance (B 20-Type, RIKEN-form)
21 - 22	High frequency choke coil
23	Fuze (Safe carrying capacity)
24	Fuse
25	Identification lights
26	Power supply circuit breaker (2 poles)
27	Power supply circuit breaker (Single pole)



TYPE 3 NARK 1 NODEL 3 RADAR Schematic Diagram of Indiscator (C-Model 1)

45

LIST OF PARTS USED IN TYPE 3 MARK 1 MODEL 3 RADAR (C - MODEL 1 INDICATOR SYSTEM)

Desig- nation	<u>Name</u>	Rating	Type-Model	Quantity
• .•	I. Types of V	acuum Tubes	F ₁	•
V1	VZ - 6C6 Vac. Tube	F63vP250V	y N • y m	1.
V 2	VZ - 6C6 Vac. Tube	F63vP250V		. 1
V3	VZ - 6C6 Vac. Tube	F63vP250V		1
٧4	VZ - 6C6 Vac. Tube	F63vP250V	•	1
V 5	VZ - 6C6 Vac. Tube	F63vP250V		, ì ·
V 6	VZ - 6C6 Vac. Tube	. F63vP250V		1
v 7	VZ - 6C6 Vac. Tube	F63vP250V		1
v 8	VZ - 606 Vac. Tube	F63vP250V		1
₹9	KX - 80, Rectifier Tube	F5V 2A		1
Vlo	KX - 142, Rectifier Tube	F2-5V,1-75A	•	1
٧ıı	BG - 75-A Cathode Tube	F2-5V,2.1A		1
Pl	Type E Bulb	10 V		1
	II. Types of	Coils Used	•	•
T1	Master Oscillator-Transformer		211-RM-42	1
T2 *	Pulse Transformer		253-SF-3	1
Т3	Coupling Transformer		201-SG-55	1
T4	Non-Coupling, Blocking Oscillator Transformer	*	201-SG-16	1
Т5	Pulse Transformer		206-FB-12	1
т6	Pulse Transformer		206-FB-12	1
17	Power Supply Transformer	- No. 1997	504-SZ-17	1
T 8	Power Supply Transformer		500 - SL-44	1
T 9	Power Supply Transformer		502-SA-53	1
^{"U} Tlo	Power Supply Transformer		502-SA-52	. 1
Ll	Scale Frequency Coil		P.B2077	1
L2	Compensation Coil		AG-13	1
L3	Filter Choke Coil	. 6	404-SK-10	1
L4	Filter Choke Coil	•	404-SK-10	1

Desig- nation	w Name	Rating	Type-Model	Quantity
<u> </u>		neous Parts	1) pc-mode1	A
J1	Concentric Cable Plug	<u></u>		1
J2	Concentric Cable Plug			1
D1	D-278 Rectifier			1
D2	D-278 Rectifier		ery or the second	1
Kl	406-N Key			1
K2	406-N Key			1
S1	Power Supply Switch	220 V 5 A		1
S2	Power Supply Change Over Switch			1
F1	Safety Fuse	220V-1A	Navy Model	_
		100V-2A	navy moder	
F2	Safety Fuse	220V-1A 100V-1A	Navy Model	1 1
		——————————————————————————————————————	*	
		Condensers		
C1	Master Oscillator Condenser 917-N4325	(1-2) 0 124 μF (1-4)0025(1-3) 0.0025 μF	917-N4000	1
C2	Coupling Condenser	0.1 µF 1 KV	M-60	1
03	By-Pass Condenser	1 µF 2 KV	KOD-1020	1
C4	Timing Condenser	0.1 μF 1 KV	M-60	1
05	Phasing Condenser	0.0005 μF 1KV	M-60	1
06	By-Pass Condenser •	1 µF 2 KV	KOD-1020	1
C 7	Blocking Oscillator Condenser	0.015 µF 1 KV	м-60	i i
C8	Coupling Condenser	1.000 µF 1 KV	76 - K	1
C9	By-Pass Condenser	1 μ F 2 KV	KOD-1020	1
C10	Coupling Condenser	0.1 µF 1 KV	M-60	1
Cll	By-Pass Condenser	1 µF 2 KV	KOD-1020	1
C12	By-Pass Condenser	1 µF 2 KV	KOD-1020	1
C13	Saw Tooth Wave Condenser	0.005 µF 1 KV	M-60	1
C14	Coupling Wave Condenser	0.005 µF 1 KV	M-60	ì

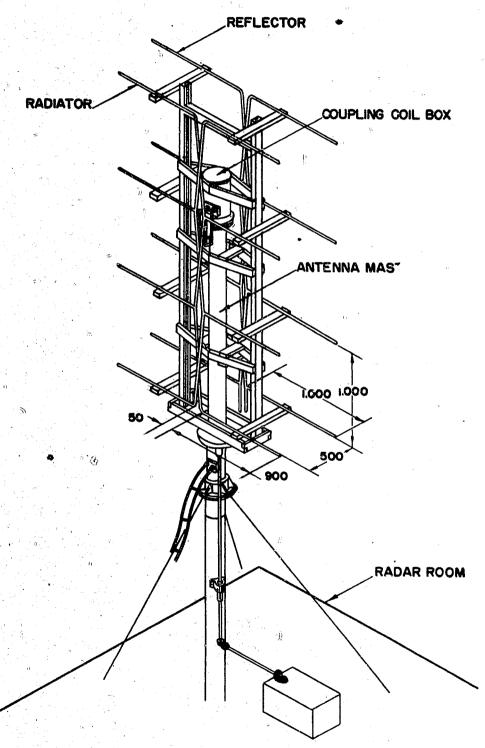
ENCLOSURE (E), continued

Desig-	Name	Poting	Type-Model	On on + 1 + m
nation		Rating		Quantity
C16	By-Pass Wave Condenser	1 μ F 2 KV	KOD-1020	i
C17	Coupling Wave Condenser	0.1 μF 1 KV	м-60	, 1
Cl8	By-Pass Wave Condenser	1 μ F 2 KV	KOD-1020	1
C19	Coupling Wave Condenser	500 PF 1 KV	16 - K	1
C20	Range Scall Oscillator Condenser	1000 200 100PF	76 - K	3
C21	Small Type Variable Condenser	100 PF	MOD-80432.	1
C22	Coupling Condenser	100 PF 1 KV	•	
C23	By-Pass Condenser	0.05 µF 1 KV	M-6 0	ĺ
025	By-Pass Condenser	0.05 µF 1 KV	M-60	1
C26	By-Pass Condenser	0.05 µF 1 KV	M-60	1
027	Coupling Condenser	0.1 µF 1 KV	M-6 0	1
C28	Coupling Condenser	1 µF 2 KV	KOD-1020	. 1
C30	By-Pass Condenser	1 μF 2 KV	KOD-1020	ı
C31	Coupling Condenser	0.1 μF 1 KV	м-60	1
032	By-Pass Condenser	1 µF 2 KV	KOD-1020	1
C33	By-Pass Condenser	1 μF 2 KV	KOD-1020	1
C34	Filter Condenser	4 μ F 2 KV	KOD-4020	1
C35	Filter Condenser	4 μ F 2 KV	KOD-4020	1
036	Filter Condenser	4 μF 2 KV	KOD-4020	1
037	Coupling Condenser	0.1 μF 3 KV	м-63	1
C38	By-Pass Condenser	1 μF 2 KV	KOD-1020	1
039	By-Pass Condenser	1 μ F 2 KV	KOD-1020	. 1
C4 0	Filter Condenser	0.5 μ F L EV	KOD-540	1
C41	Filter Condenser	0.5 μF 4 KV	KOD-540	1 .
	V. Types of Vari	able Resistors		
VRl	Phasing Variable Resistor	500 K Ω	NV-35-B	1
VR2	Blocking Oscillator Variable Resistor	∕20 KΩ	NV-35-B	. 1
VR3	Time Axis Amplitude Resistor	500 ΚΩ	NV-35-B	1
VR4	Graduated Cylinder Resistor	3 Κ Ω	NV-35-B	1

Desig-		~~		2.5 s
nation	<u>Name</u>	Rating	Type-Model	Quantity
VR5	Signal Input Resistor	10 K Ω	NV-1	1
VR6	Horizontal Adjustor Resistor	500 K Ω	NV-B	1
VR7	Vertical Adjustor Resistor	500 K Ω	NV-B	1
VR8	Focus Adjustor Resistor	100 ΚΩ	NV-B	1
VR9	Degree of Illumination Adjustor Resistance	100 Κ Ω	NV-B	1
	VI. Types of I	Fixed Resistors		
Rl	Grid Leakage Resistor	10 Κ Ω	C-2	
R2	Screen Grid Voltage Divider Resistor	50 Κ Ω	C-2	1
R3	Screen Grid Voltage Divider Resistor	50 Κ Ω	C-2	1
R4	Grid Divider Resistor	25 K Ω	C-2	1
R5	Grid Divider Resistor	10 Κ Ω	C-2	1
R6	Anode Series Resistor	100 Κ Ω	C-2	1
R7	Blocking Oscillator Cathode Resistor	100 Κ Ω	C-2	1
R8	Grid Leakage Resistor	50 K Ω	C-2	1
R9	Catnode Resistor	5 Κ Ω	C-2	'l
R10	Bias Resistor	20 K Ω	C-2	1
Rll	Voltage Divider Resistor	100 K U	C-2	1
R13	Coupling Resistor	500 KΩ	C-2	1
R14	Bias Resistor	20 K Ω	C-2	1
R15	Voltage Divider Resistor	100 K Ω	C-2	1
R16	Voltage Divider Resistor	50 KΩ	C-2	1
R17	Saw Tooth Wave Nascent Resistor	500 KΩ	C-2	1
R18	Bias Resistor	1 K O	C-2	1
R19	Voltage Divider Resistor	50 KΩ	C-2	1
R20	Voltage Divider Resistor	20 K Ω	C-2	ı
R21	Anode Resistor	50 KΩ	C-2	1

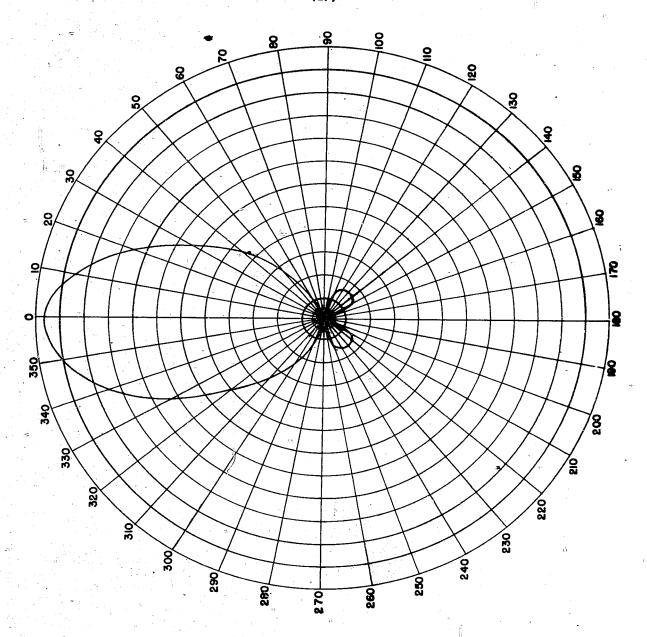
ENCLOSURE (E), continued

Desig- nation	<u>Name</u>	Rating	Type-Model	Quantity
R22	Coupling Resistor	500 KΩ	C-2	1
R23	Grid Leakage Resistor	100 Κ Ω	C-2	.1
R24	Voltage Divider Resistor	50 Κ Ω	C-2	. 1
R25	Voltage Divider Resistor	50 ΚΩ	C-2	1
R26	Resistor	10 ΚΩ	C-2	1
R28	Bias Resistor	100 ΚΩ	C-2	1
R29	Voltage Divider Resistor	50 KΩ	C-2	1
R30	Voltage Divider Resistor	50 ΚΩ	C-2	1
R31	Anode Load Resistor	2 K Ω	C-2	1
R32	Coupling Resistor	100 KΩ	C-2	1
R34	Bias Resistor	2 K O	C-2	1
R35	Screen Grid Resistor	50 ΚΩ	C-2	1
R36	Anode Resistor	25 K Ω	C=2	1
R37	Coupling Resistor	500 KΩ	C-2	1
R38	Voltage Divider Resistor	250 ΚΩ	C-2	1
R39	Voltage Divider Resistor	250 ΚΩ	C-2	1
R40	Voltage Divider Resistor	250 ΚΩ	C-2	1
R41	Voltage Divider Resistor	500 Κ Ω	C-2	1
R42	Voltage Divider Resistor	30 0 ΚΩ	C-2	1,.
R43	Voltage Divider Resistor	300 KΩ	C-2	1
R44	Voltage Divider Resistor	100 KΩ	C-2	1
R45	Voltage Divider Resistor	200 ΚΩ	C-2	1
R46	Coupling Resistor	100 ΚΩ	C-2	1
R47	Coupling Resistor	100 ΚΩ	C-2	l
R48	Filter Resistor	100 ΚΩ	C-2	ı
R49	Filter Resistor	5 KΩ	C-2	1

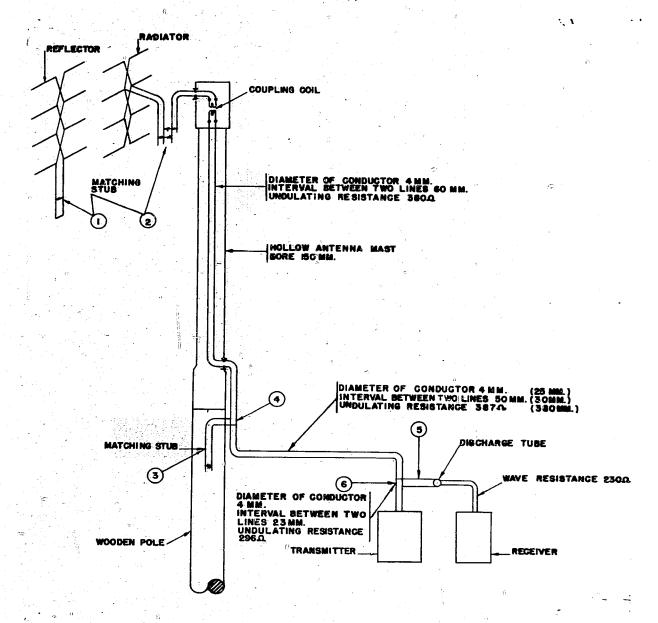


TYPE 3 MARK 1 MODEL 3 RADAR Construction of the Antenna

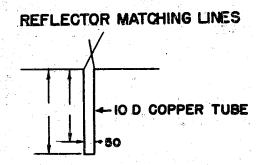
ENCLOSURE (E), continued



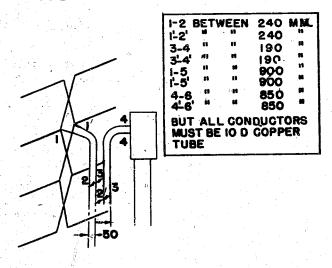
TYPE 3 MARK 1 MODEL 3 RADAR Antenna Directivity Pattern



TYPE 3 MARK 1 MODEL 3 RADAR Schematic Diagram of Antenna

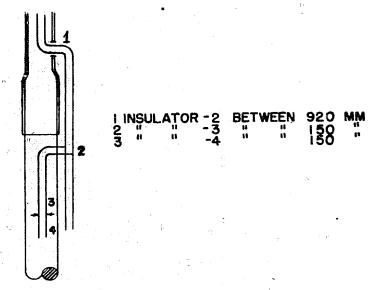


RADIATOR MATCHING LINES

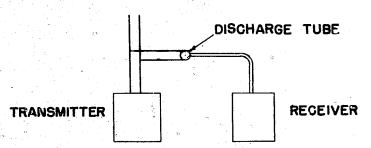


TYPE 3 MARK 1 MODEL 3 RADAR

FEEDER LINE MATCHING LINES



RECEIVING CIRCUIT BRANCHING POINTS



TYPE 3 MARK 1 MODEL 3 RADAR

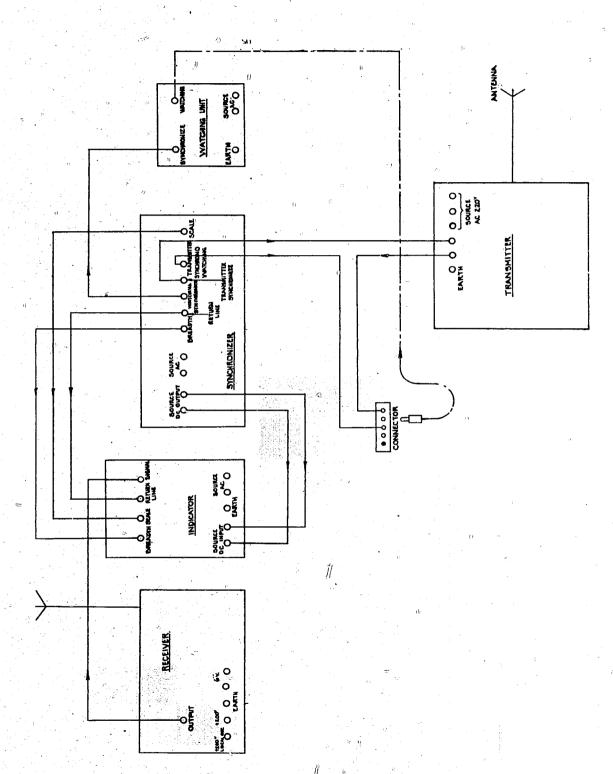
ENCLOSURE (F)

WIRING DIAGRAMS OF TYPE 2 MARK 2 MODEL I RADAR

LIST OF DIAGRAMS

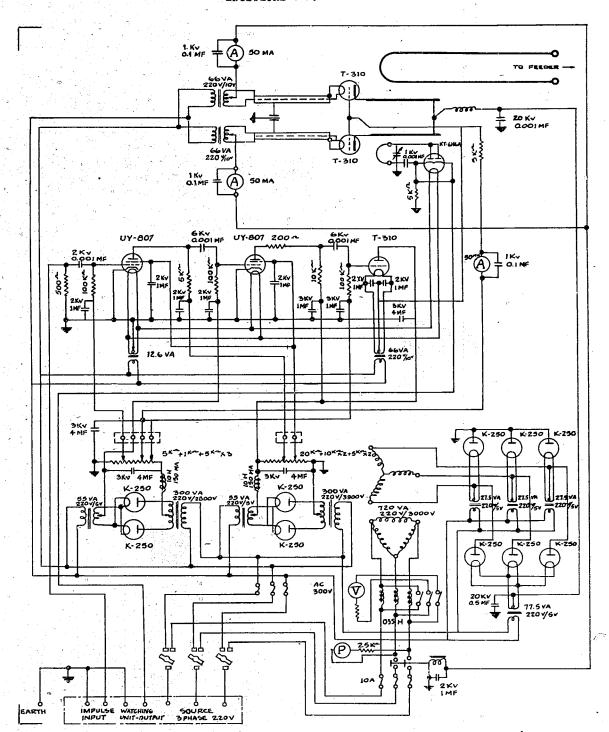
Connection Diagram Between Units (Also applicable to 2-11 and 2-12) .	Page	57
Transmitter Connection Diagram (Also applicable to 2-12)	Page	58
Receiver Connection Diagram (Also applicable to 2-11 and 2-12)	Page	59
Rectifier for Receiver Connection Diagram (Also applicable to		
2-11 and 2-12)	Page	60
Indicator Connection Diagram (Also applicable to 2-11 and 2-12)	Page	61
Synchronizer Connection Diagram (Also applicable to 2-11 and 2-12)	Page:	62
Watching Unit Connection Diagram (Also applicable to 2-11 and 2-12) .	Page	63
Automatic Voltage Regulator (Also applicable to 2-11, 3-11, 2-12,	_	
and 3-13)	Page	64
Wave Meter (Also applicable to 2-11, 3-11, 2-12, and 3-13)	Page	65

ENCLOSURE (F), continued



TYPE'S MARK 2 NOBEL 1 RADAR Connection Diagram Between Units

ENCLOSURE (F), continued



Transmitter Connection Diagram

IN LOCAL OSC.

IN DET.

= 50 PF

2 94

50 KT

VN-955

UN-95

0.002,45

3002

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LHIGH FREQUENCY AMPLIFIER IS SINGLE TUBE (UN-954)

THE RADAR MODEL 2-11

UN-954

H.F. AMP.

TO FEEDER

002

E I. M.F. AMP.

ZMO DET

2 NR LOCAL OSC.

RE-3

PLATE SOURCE

I KA

FILAMENT SOURCE

SOURCE

0.002.4

30 KM

100 Kπ

L.F. AMP.

mo-1

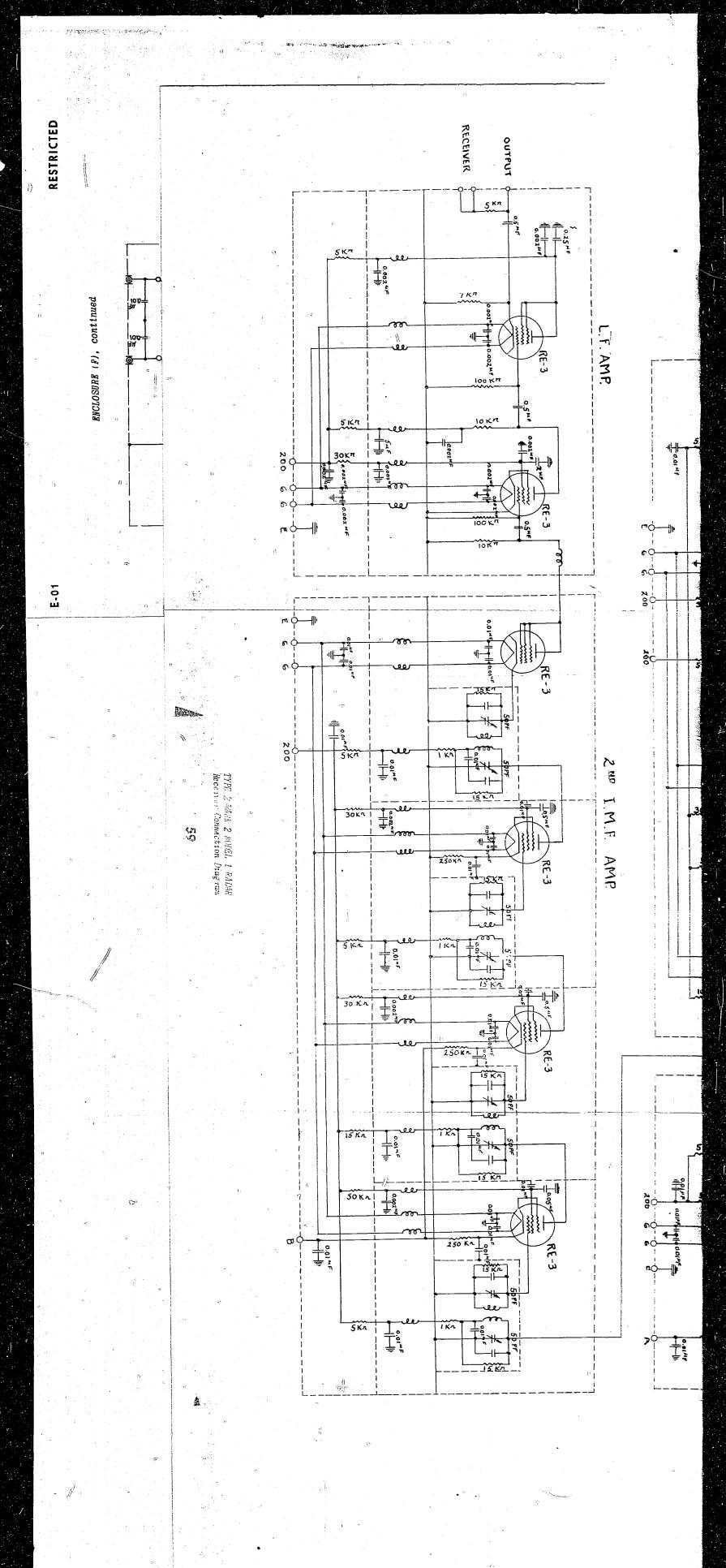
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80

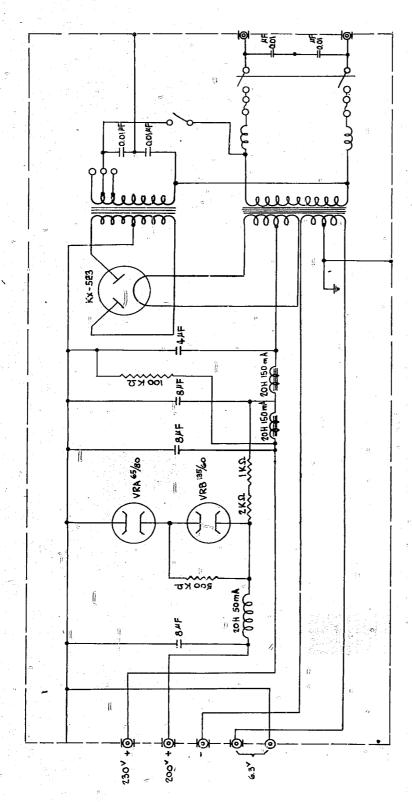
25 I.M.F. AMP.

5 K# 0.002/16 I K#

0.002 Hr

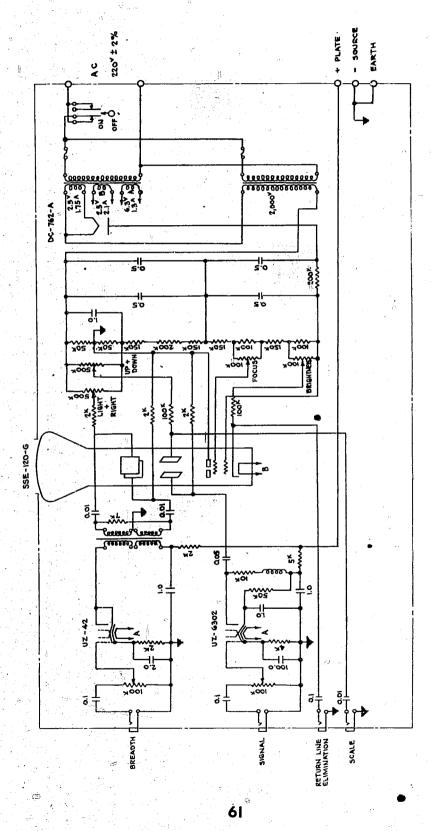


ENCLOSURE (F), continued



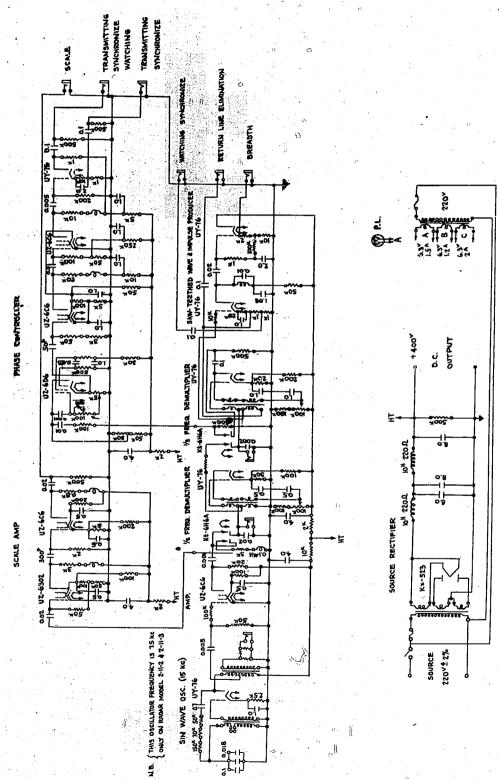
TYPE 2 MARK 2 MODEL 1 RADAR Rectifier for Receiver Connection Diagram

ENCLOSURE (F), continued



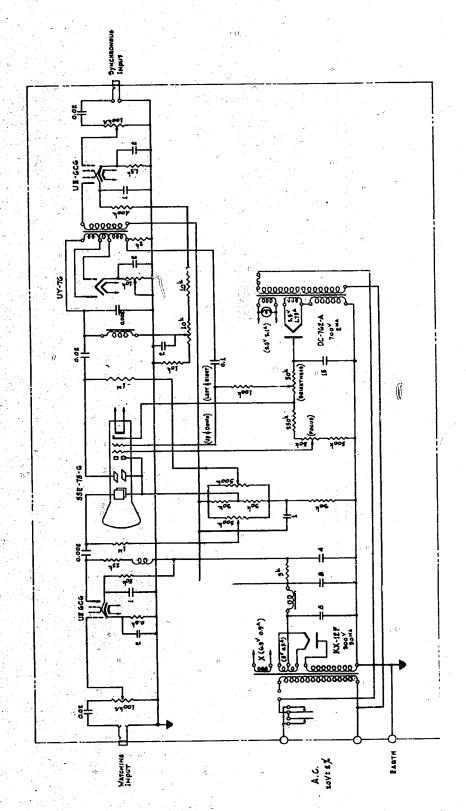
Indicator Connection Diagram TYPE 2 MARK 2, MODEL 1 RADAR

ENCLOSURE (F), continued



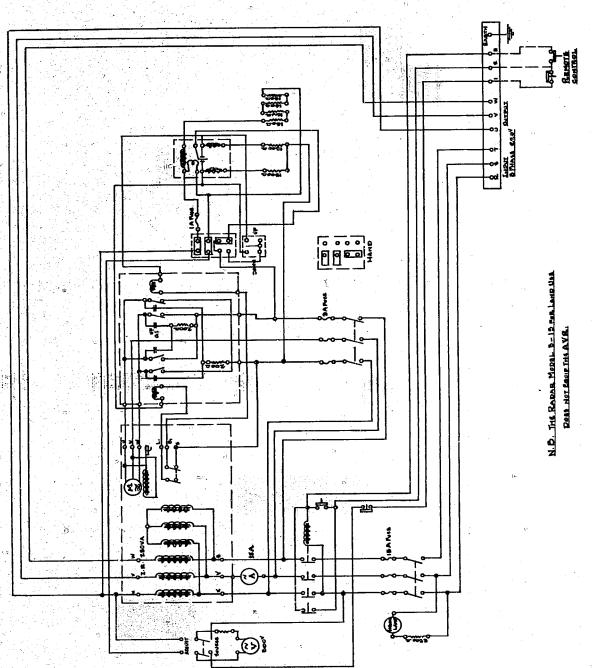
TYPE 2 NARK 2 MODEL 1 RADAR Synchronizer Connection Diagram

ENCLOSURE (F), continued

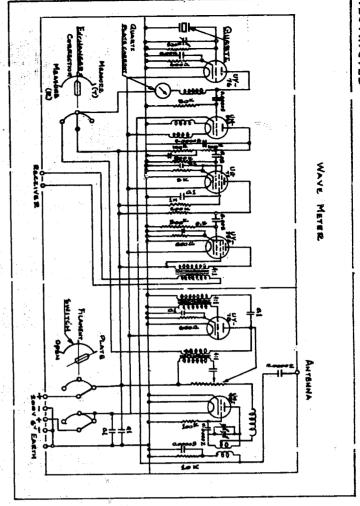


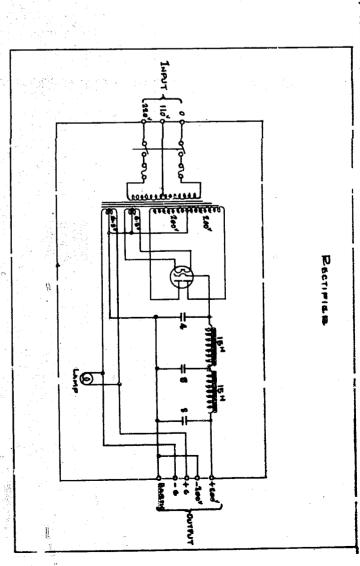
TYPE 2 NARK 2 NODEL 1 RADAR Watching Unit Connection Diagram

ENCLOSURE (F), continued

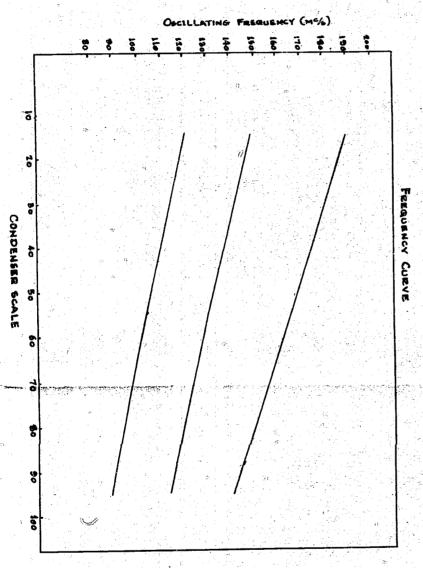


TYPE & WARK 2 WODEL 1 RADAR Automatic Voltage Regulator





WAVE METER



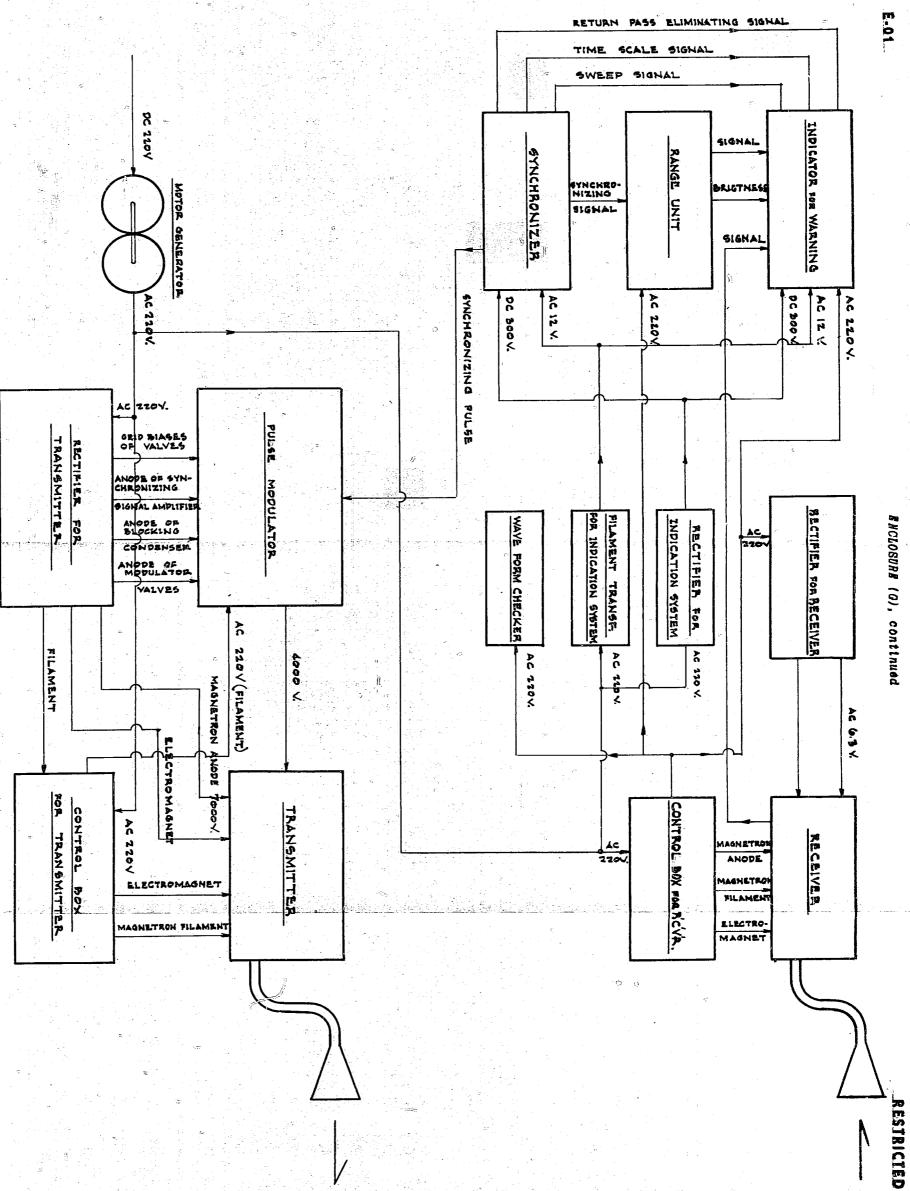
N.B. THE RADAR MODEL 9-19 TARLAND USE DOES NOT EQUIPTIES WAVE METER:

ENCLOSURE (G)

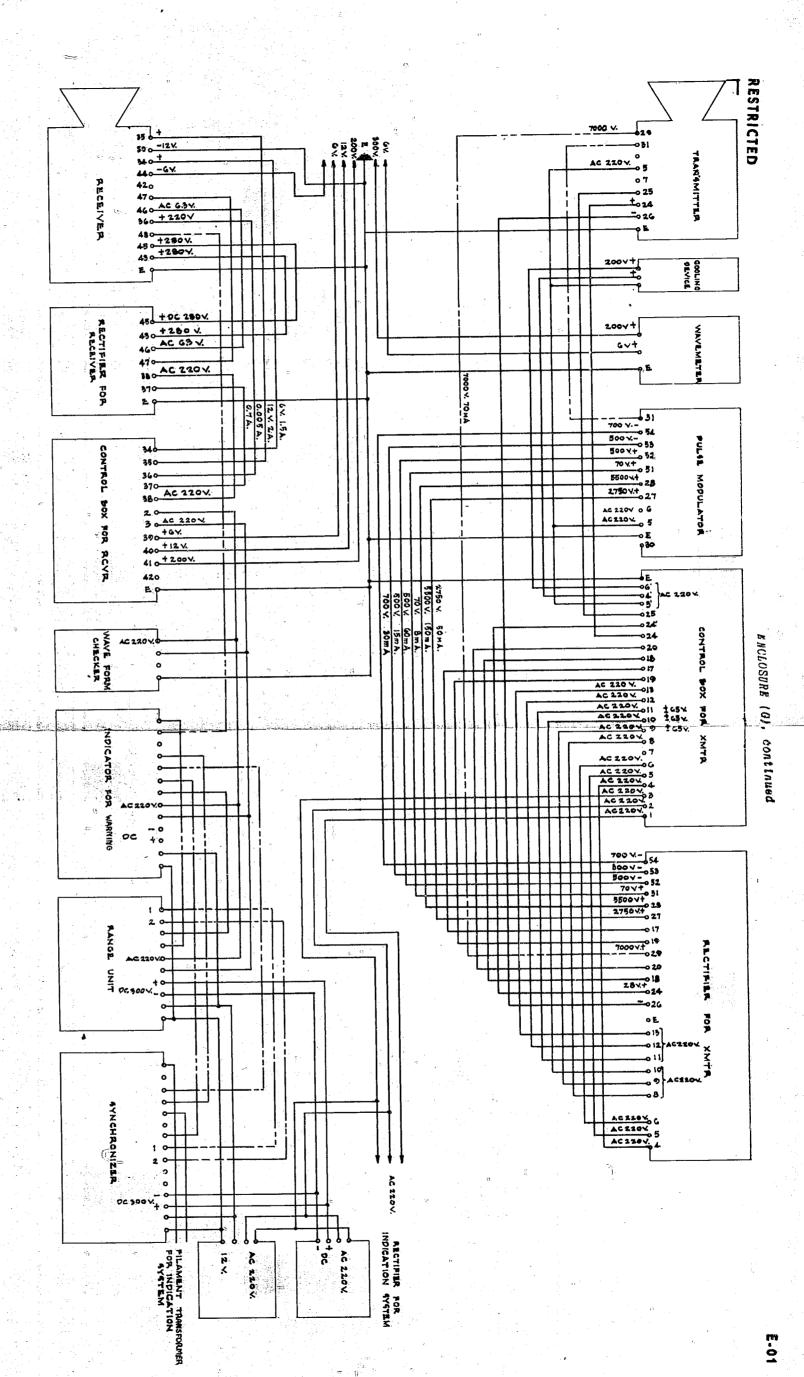
WIRING DIAGRAMS OF MARK 2 MODEL 2 MODIFICATION 4 RADAR

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Connection Diagram of Receiver	LORG.	()
Connection Diagram of Pulse Modulator	rage	17
Constant Voltage Apparatus and Rectiller and	Page '	77

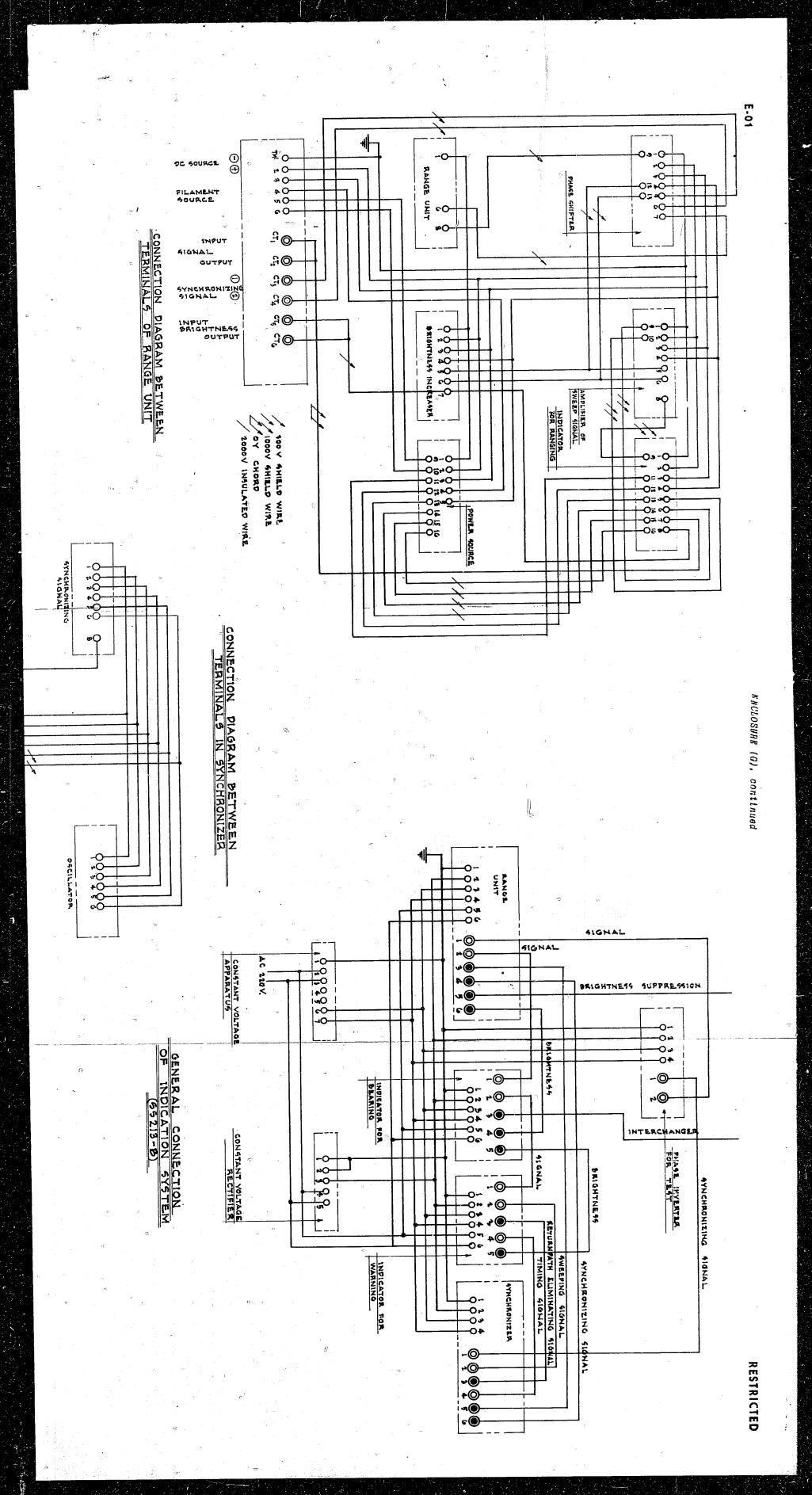


NARK 2 NODEL 2 NODIFICATION 4 RADAR Block Dragram



MARK' 2 HODEL 2 HÖDIFICATION & RADAR Wiring Diagram

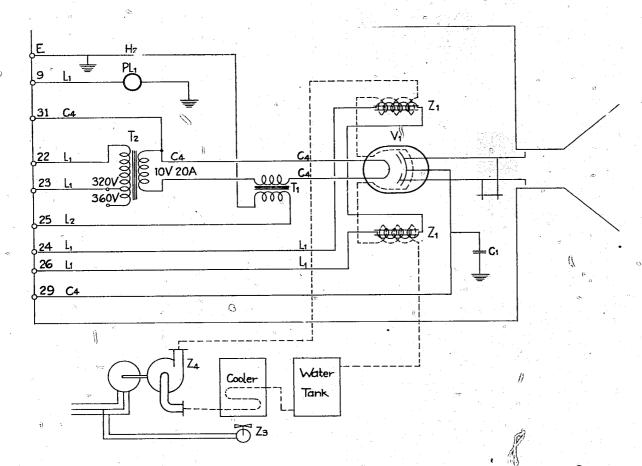
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E-01

OSCILLATOR

ENCLOSURE (G), continued



C ₁	Oil Filled Condenser	1	2uF, TVDC20kV
PL,	Pilot Lamp	1	24V 0,11A
T,	Current Transformer	1	50~15VA, TVACIOKV
T ₂	Cathode Heating Transformer	<u>-</u> 1	Pr. 200V& 220V, Sec. 10V 20A, TVAC10kV
V ₁	Magnetron	1	M-312
Z,	Electromagnet	- 1	16mmD5C2500T×2(8,9Ω×2)
Z ₃	Electric Fan	1	701 /sec, AC220V, 50%
Z ₄	Cooling Pump	1	16,51 sec, AC220V,50%

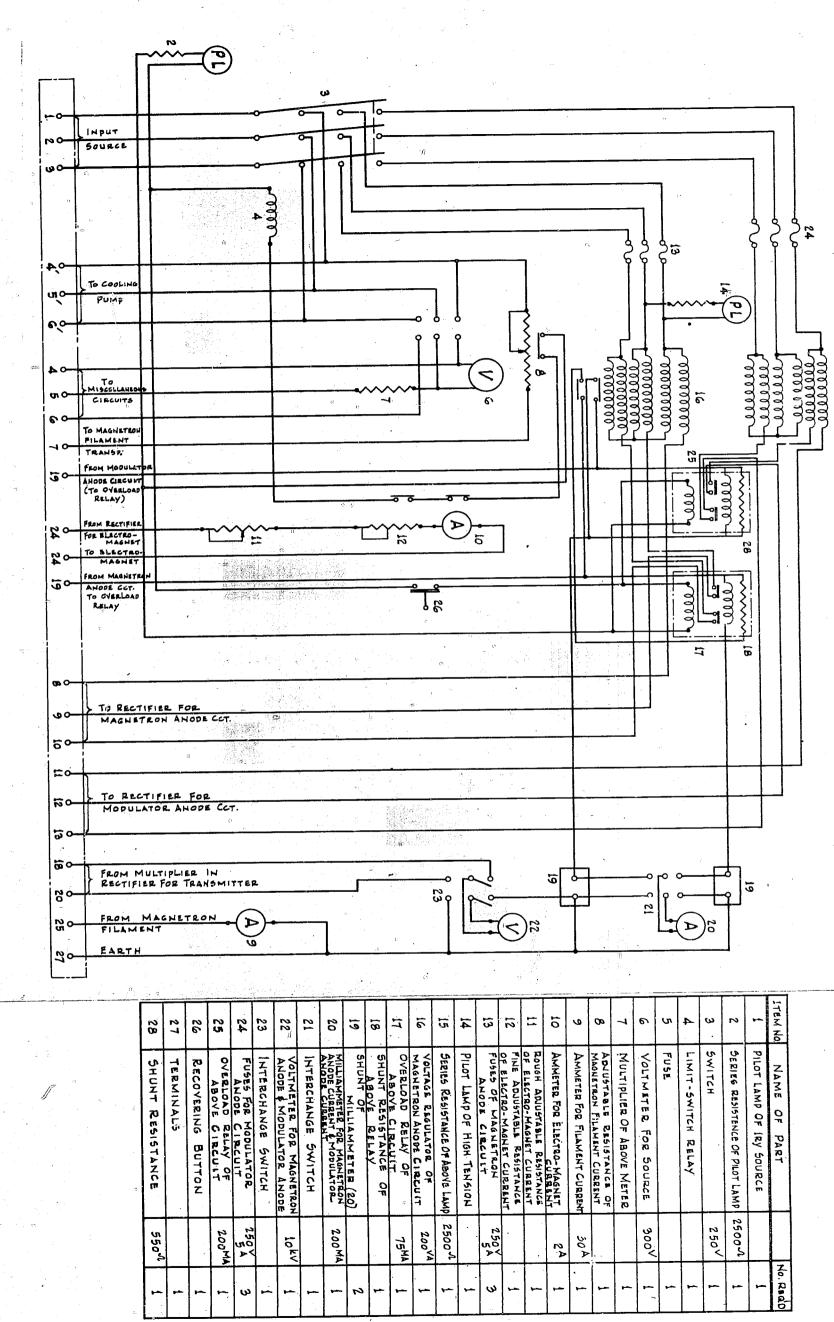
MARK 2 MODEL 2 MODIFICATION 4 RADAR Transmitter

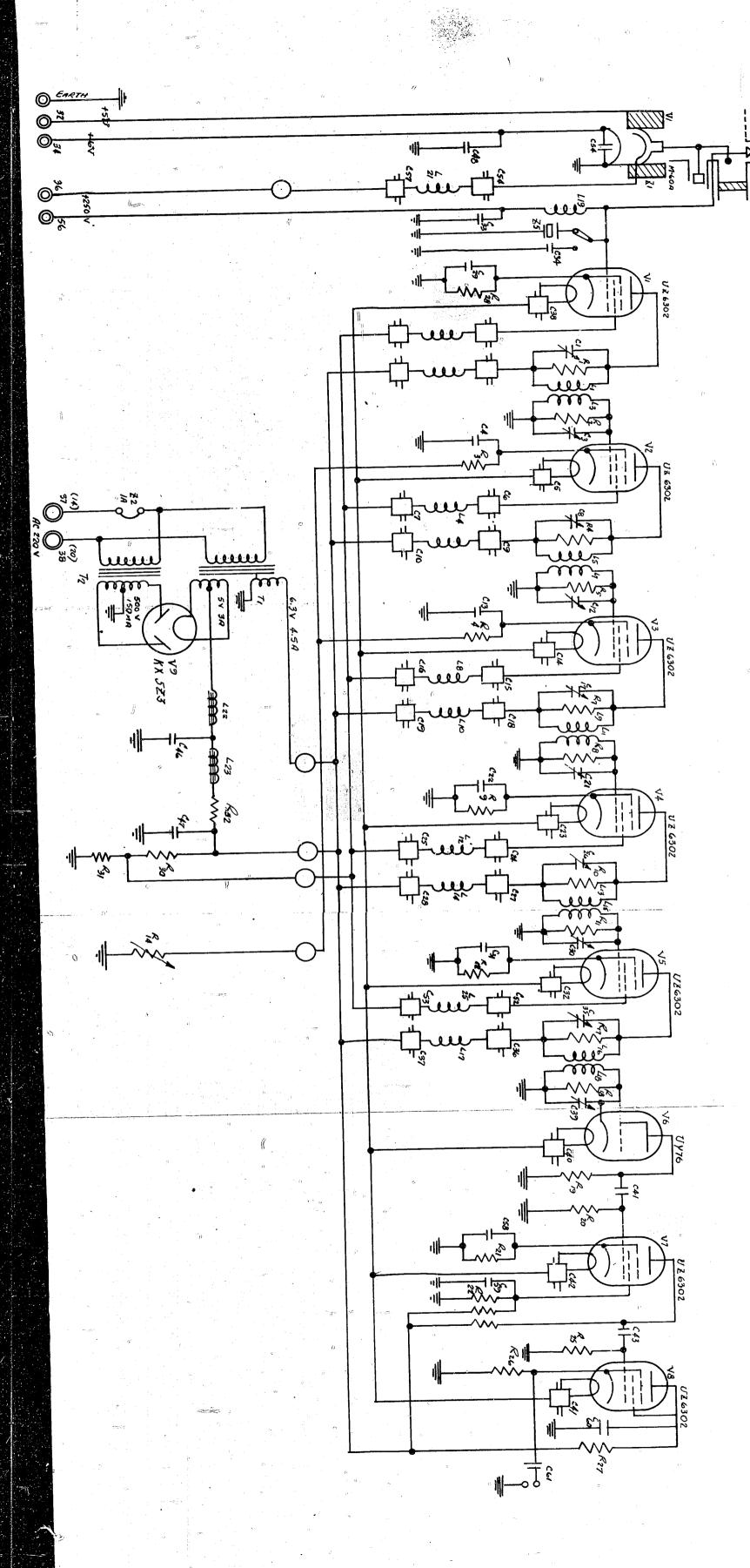
ENCLOSURE (G), continued

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MARK'2 MODEL'2 MODIFICATION : RADAR Connection Diagram of Rectifier for Fransmitter

NARI 2 NODEL 2 NODEFICHTON 4 BABBAR Circuit Diagram of Control Box for Trunsmitter





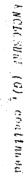
ENCLOSURE (G), continued

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ASSESS VALTAGE CONTROL
ALOSE VOLTAGE
ADMATORER CELEB
THERMENT CURRENCE
ESMATRIGE SOUTHON
THERRUS THEMALIT
THAL TOLIS
INTERCHANDE SWITCH
HOTIWA
ATM THERRO CURRENT MTR
AMTEN THERRUD BOOMA
(ABTEM THERRUS JATHTRS HTM
HOMMON WELLEN BOALTON BOOMY
RETEM THERRUS THEMALIS
THAL TOLIT ANT ASMANGEMANT

NARK 2 MODEL 2 MODIFICATION 4 RADAR Connection Diagram of Receiver

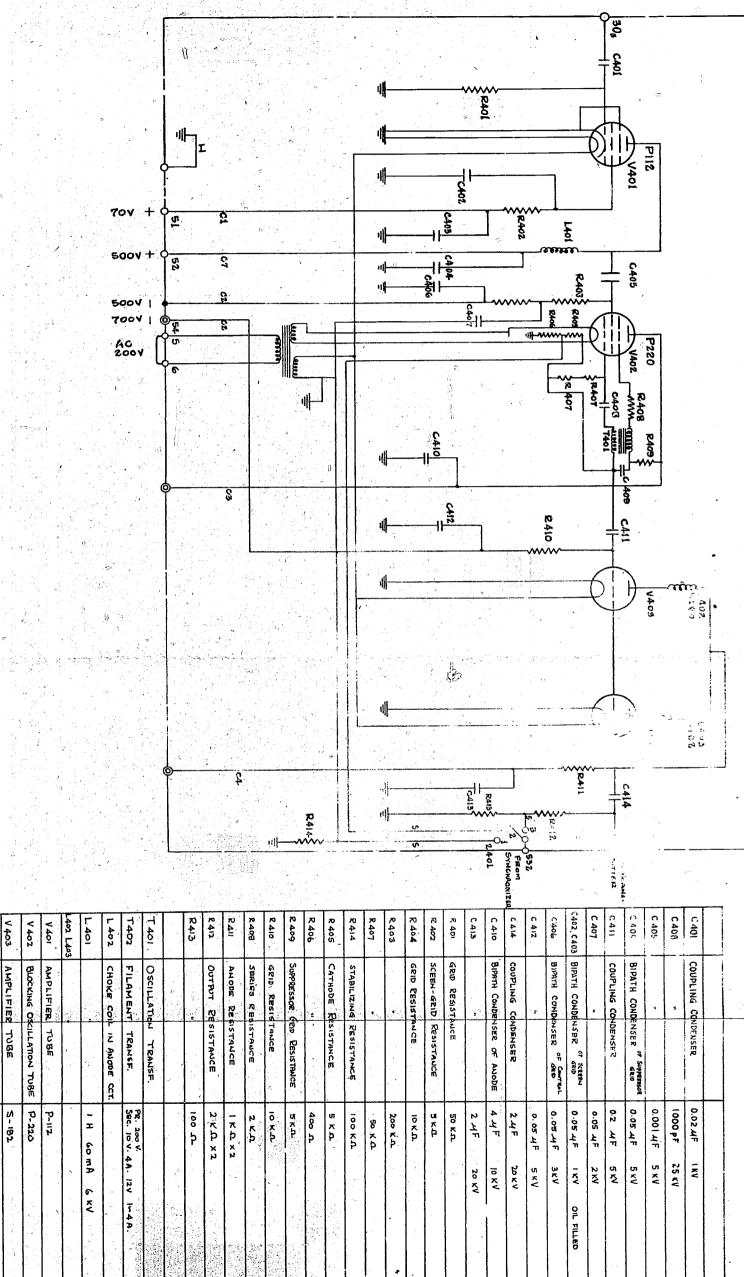
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	0.1 MF	NBCS		;	0.1MF	NBCSD	;	;	0.1MF	W2000	"		NBC SP			U8-6302	KX-583	"	UB-6302	UY- 76	"	44	"	18.630Z	M-60A	
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NARK 2 NODEL 2 NODIFICATION 4 RADAR Connection Diagram of Palse Modulator

V 404

V 403

AMPLIFIER TUBE

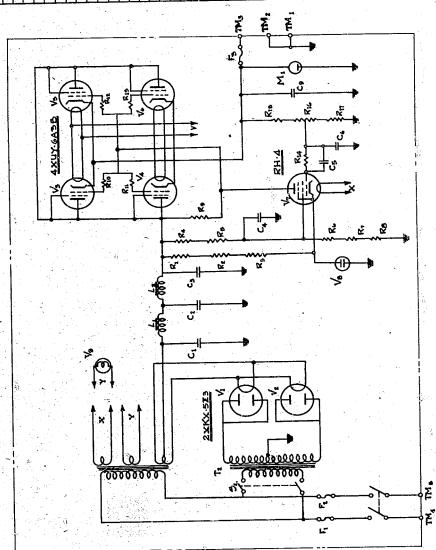
ENCLOSURE (G), continued

1 1 10V, 0.18A 1 10V, 0.18A 1 1 10V, 0.18A 1 1 10V, 0.18A 1 1 100V, 0.18A 1 1 100V, 0.18A 1 1 1 100V, 0.18A 1 1 1 100V, 0.18A 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 20H 30mA 1 20H 30mA 1 10KG 1 10KG 1 50KG 1 50KG 1 5KG	1 5KG 1 5KG 1 5KG 1 25KG 1 25KG 1 5KG 1 20KG		1 250V AC 1 3A 1 3A 1 3A	
KX-80 UV-211A RH-2 //RA *8/50					200
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MARK 2 MODEL 2 MODIFICATION 4 RADAR Constant Voltage Apparatus

ENCLOSURE (G), continued

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MARK 2 NODEL 2 MODIFICATION 4 RADAR Constant Voltage Rectifier

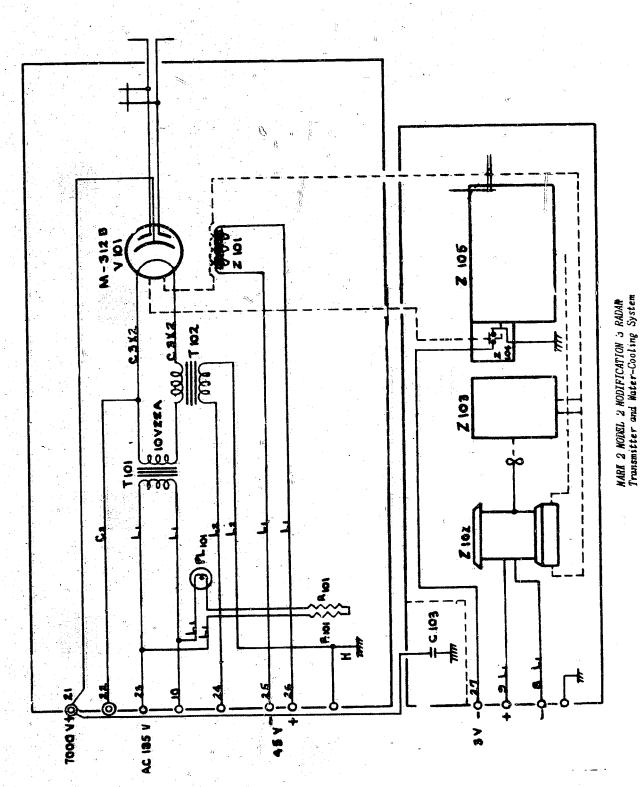
## ENCLOSURE (H)

WIRING DIAGRAMS OF MARK 2 MODEL 2 MODIFICATION 3 RAMAR

## LIST OF DIAGRAMS

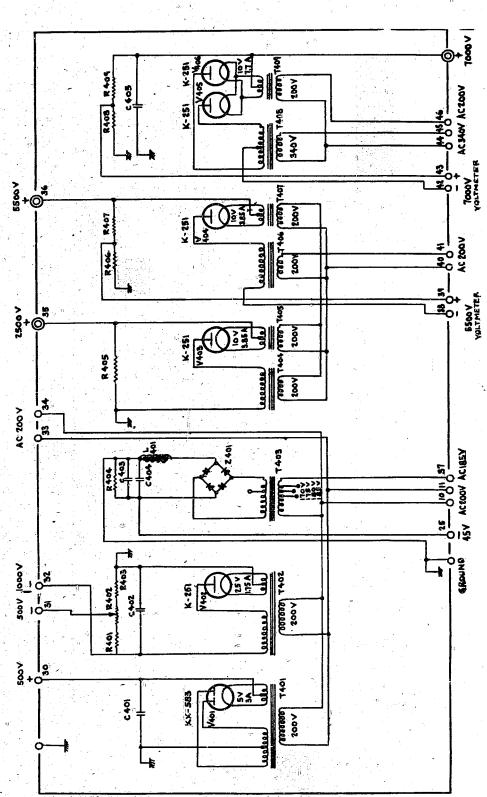
Transmitter and Water - Cooling System	. Page	79
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Transmitter Rectifier	• Lago	93
Turning Modulator Circuit	• EGRe	01
Indianton System Circuit	• rage	02
Transmitter - Receiver Controller	• Page	83

ENCLOSURE (H), continued

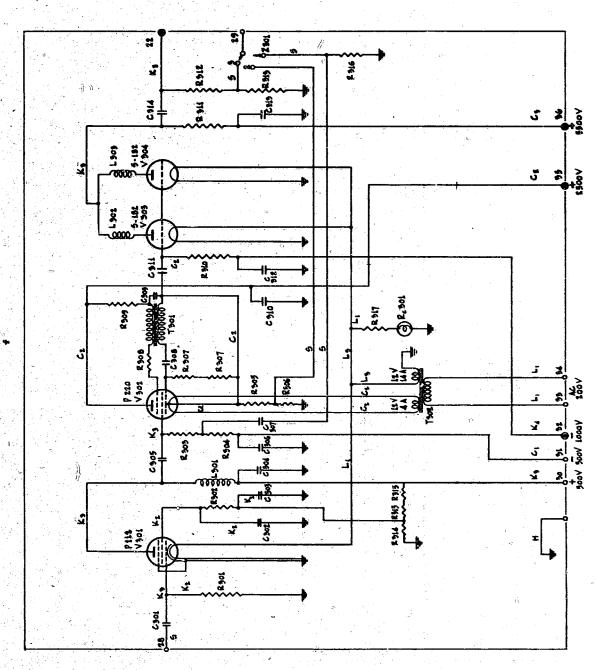


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ENCLOSURE (H), continued

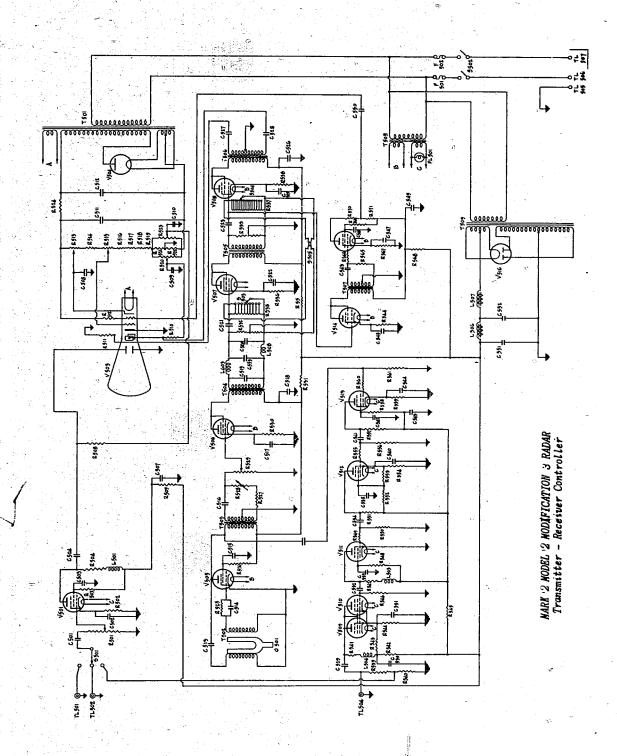


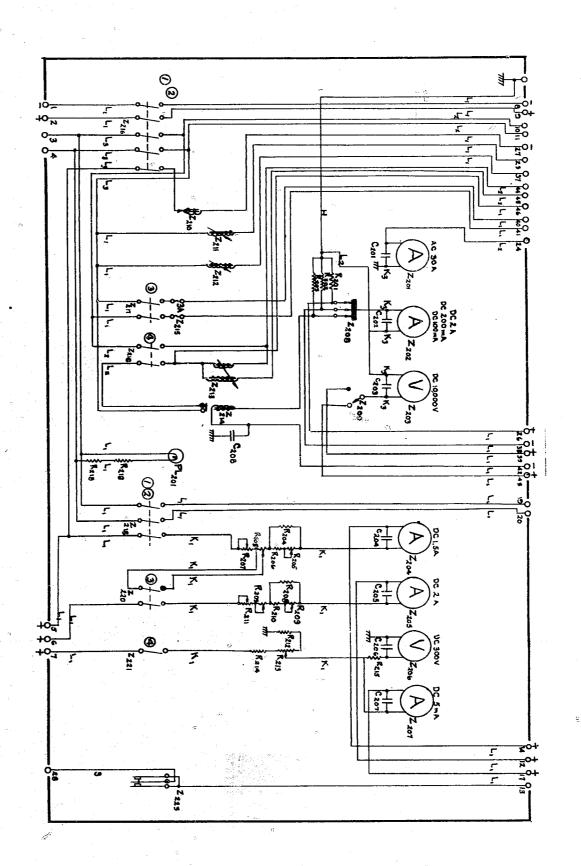
MARK 2 NODEL 2 NODIFICATION 3 RADAR Transmitter Rectifier



NARR 2 NODEL 2 NODIFICATION S RADAR Impulse Nodulator Circuit

ENCLOSURE (H), continued





NARE 2 HODEL 2 HODEFICATION 3 RADAR Indicator System Circuit